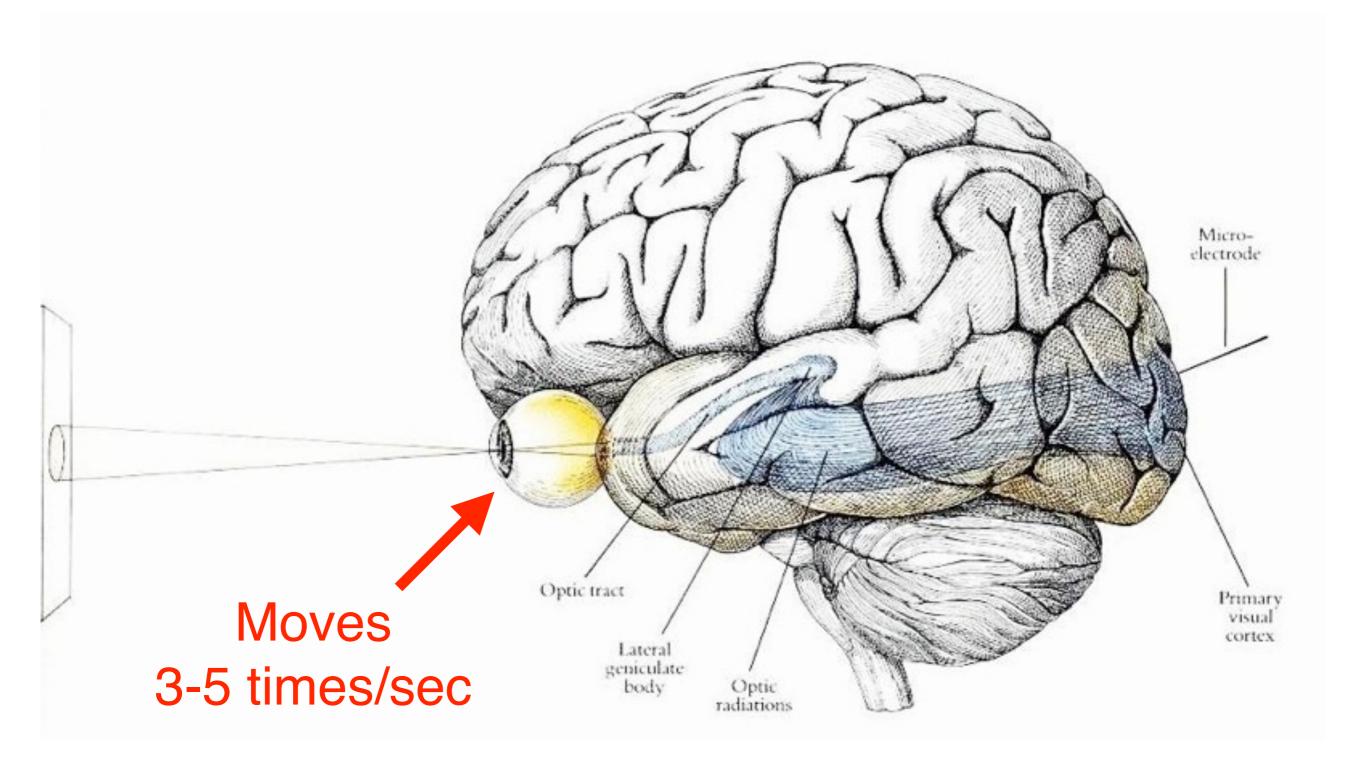
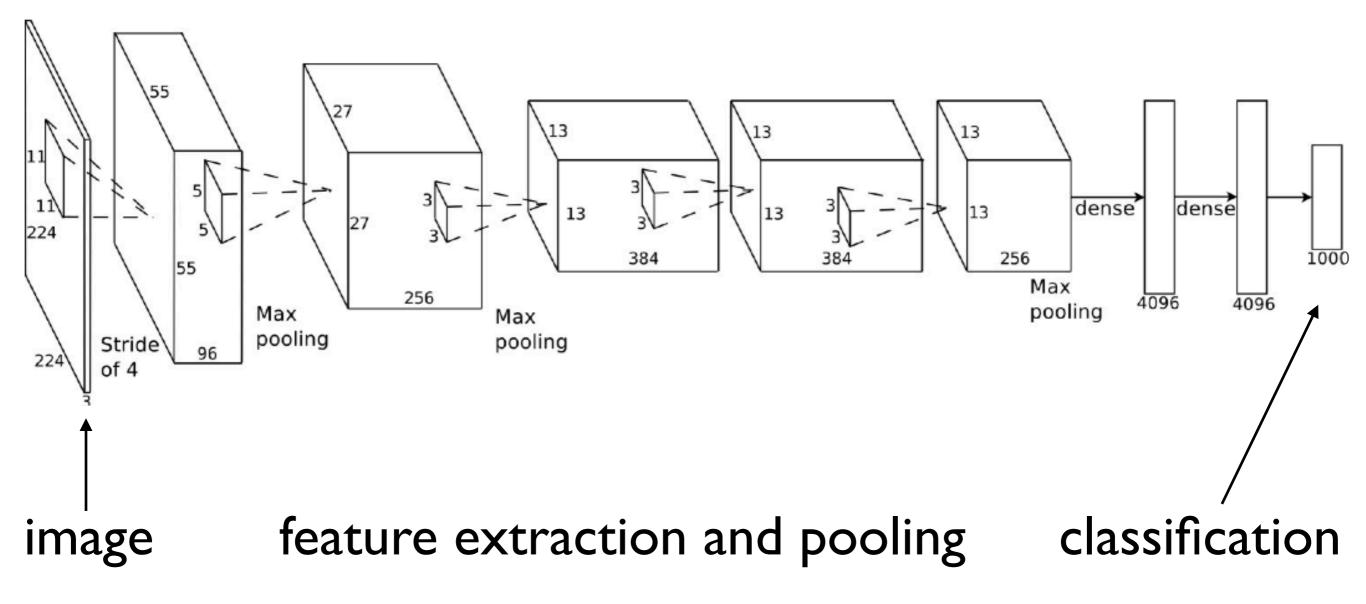
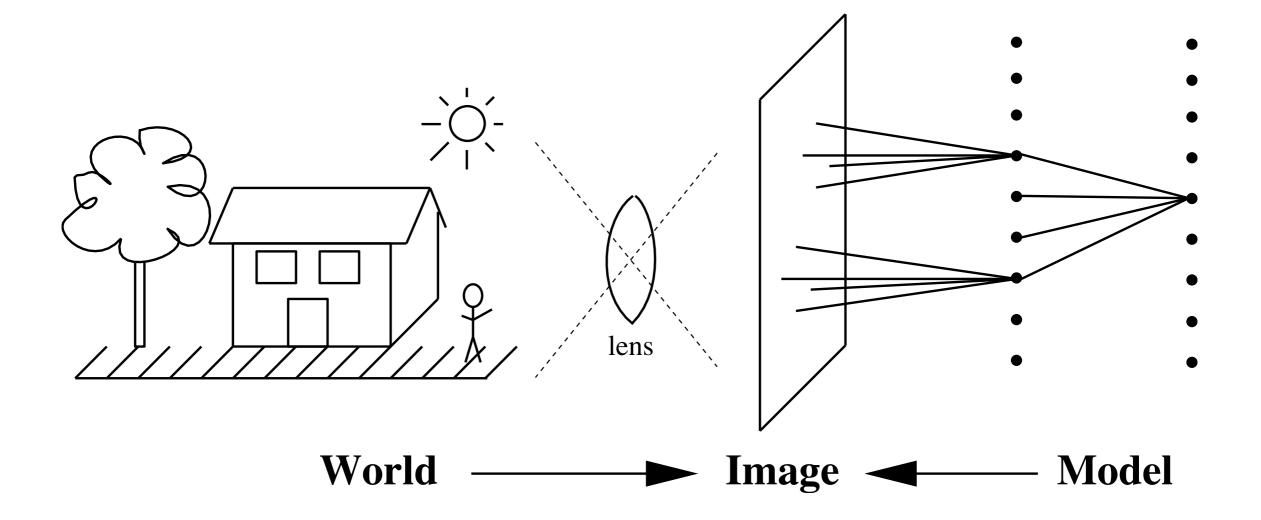
# What are the principles governing information processing in this system?



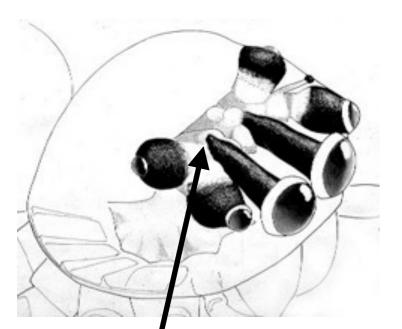
#### 'AlexNet' (Krizhevsky, Sutskever & Hinton 2012)



## Vision as inference



#### Active vision in jumping spiders



(Wayne Maddison)



(Bair & Olshausen, 1991)

## One-day old jumping spider (filmed in the Bower lab, Caltech 1991)



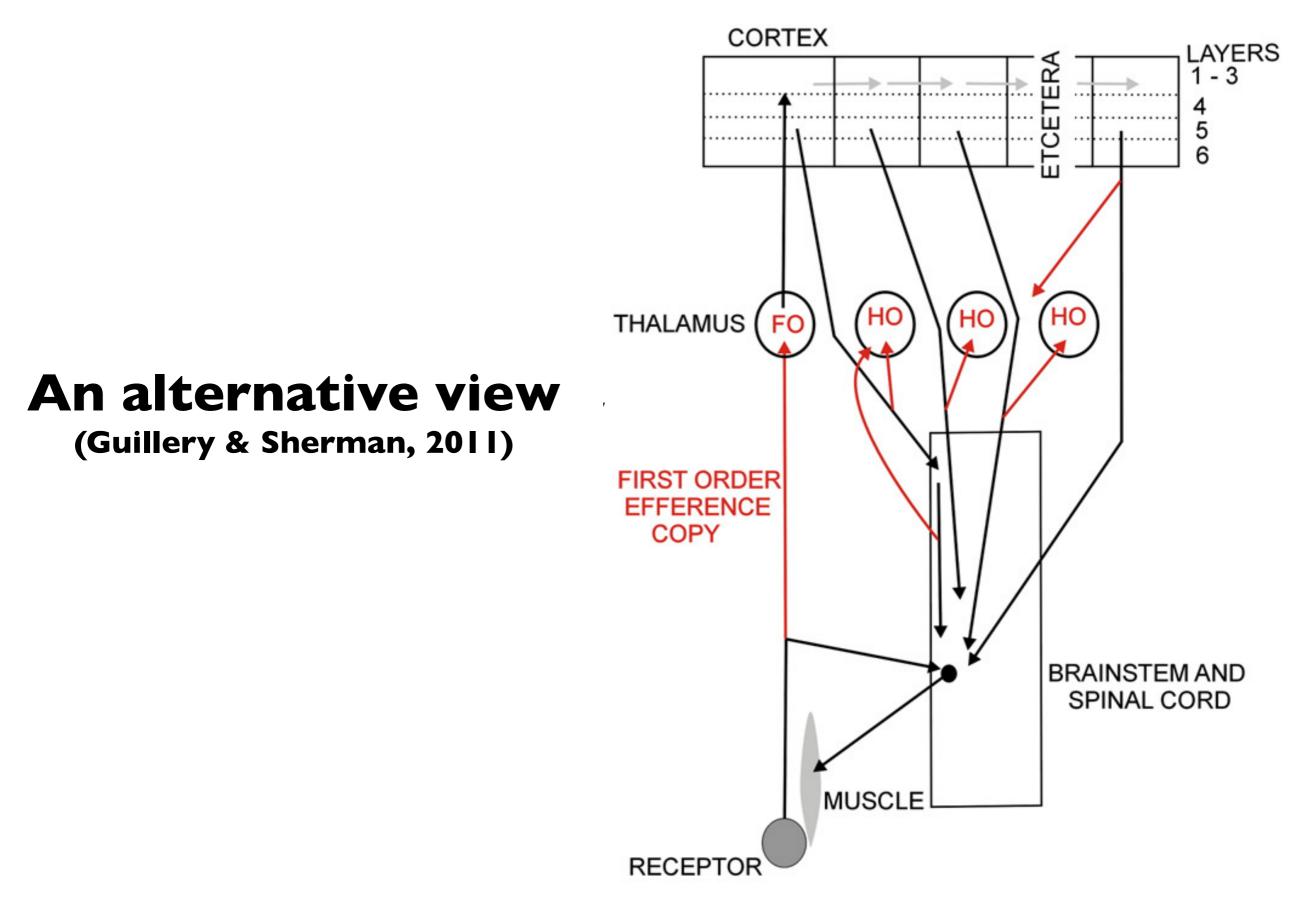
#### One-day old jumping spider (filmed in the Bower lab, Caltech 1991)



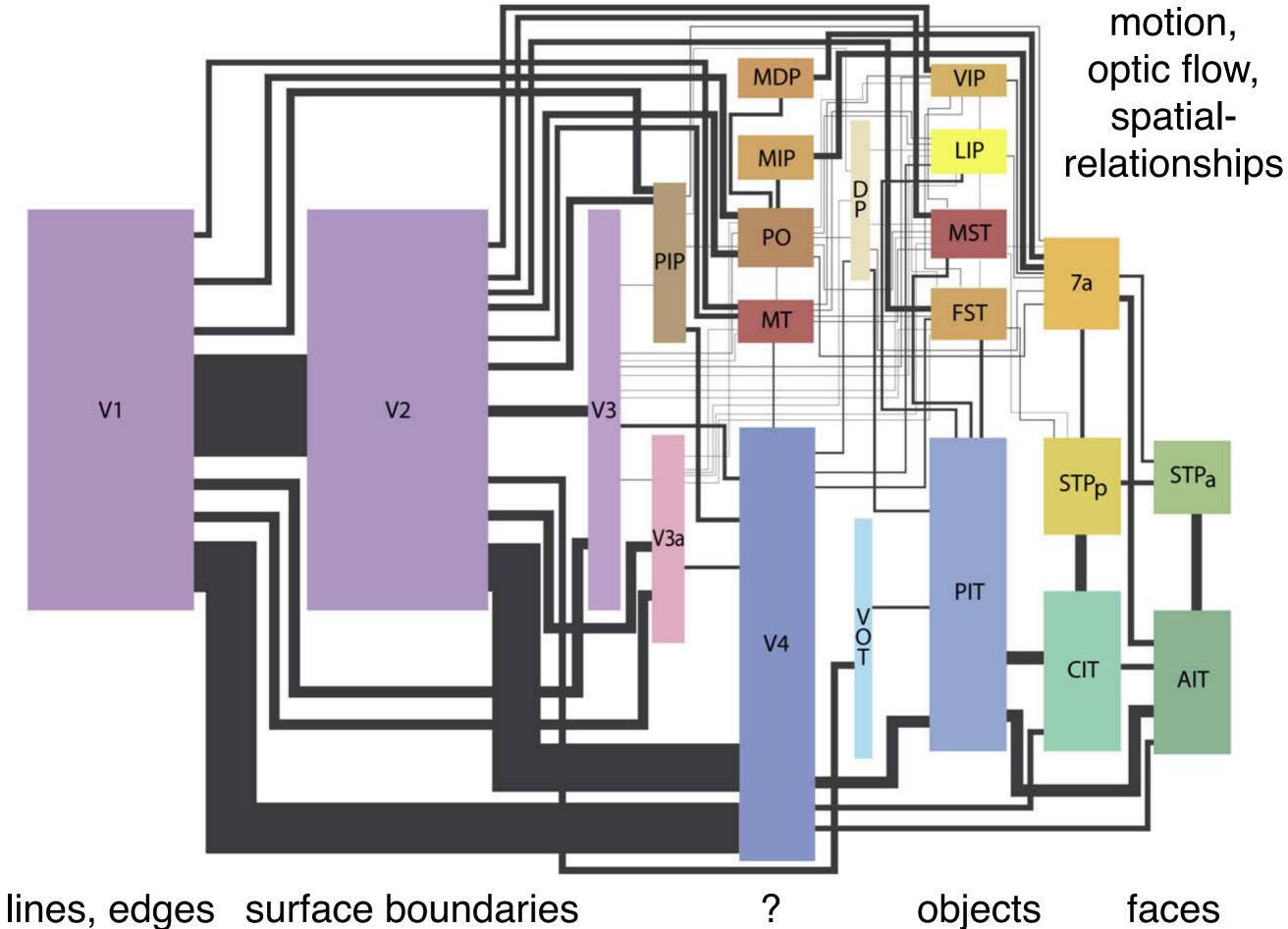
...problem solving behavior, language, expert knowledge and application, and reason, are all pretty simple once the essence of being and reacting are available. That essence is the ability to move around in a dynamic environment, sensing the surroundings to a degree sufficient to achieve the necessary maintenance of life and reproduction. This part of intelligence is where evolution has concentrated its time--it is much harder.

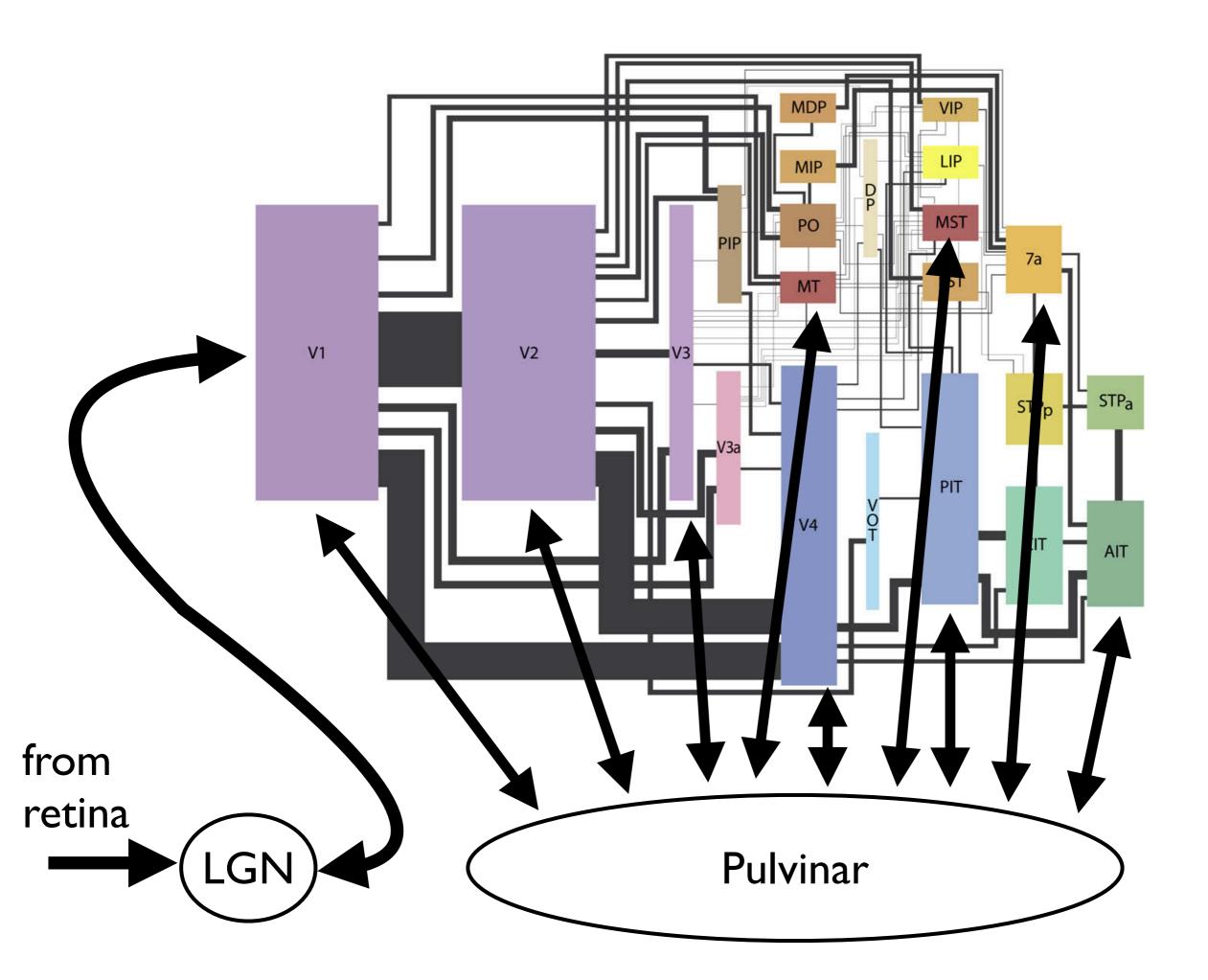
— Rodney Brooks, "Intelligence without representation," Artificial Intelligence (1991)

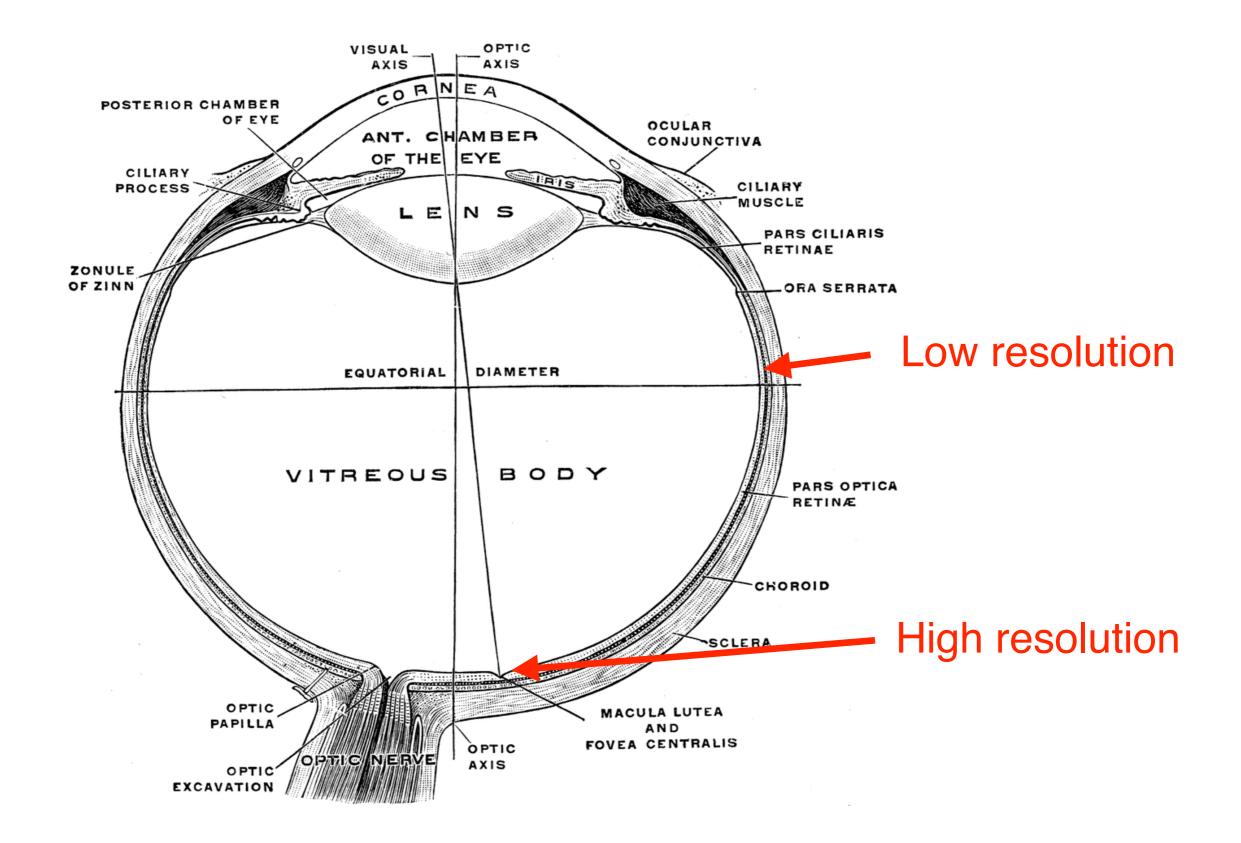




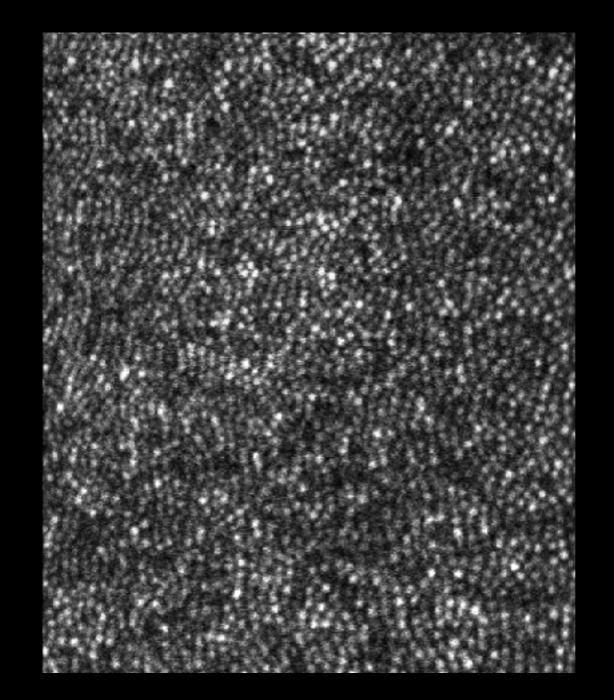
Wallisch & Movshon (2008)







# Fixational eye movements (drift)



(from Austin Roorda, UC Berkeley)

## Super-resolution in the Google Pixel camera

#### image displacements from natural hand tremor ٠ • • • ٠ • • • ٠ • • • . ٠ . • ٠ • • ٠ • 1<sup>st</sup> frame (base frame) 2<sup>nd</sup> frame 3<sup>rd</sup> frame 4<sup>th</sup> frame All frames aligned to base frame fred to use the space on a first-con with Komp in mind that success in to use it at their bo 0.15 x displacement y displacement of free to use the space on a first-come basis. Keep in mind that somebody pop-in to use it at their books

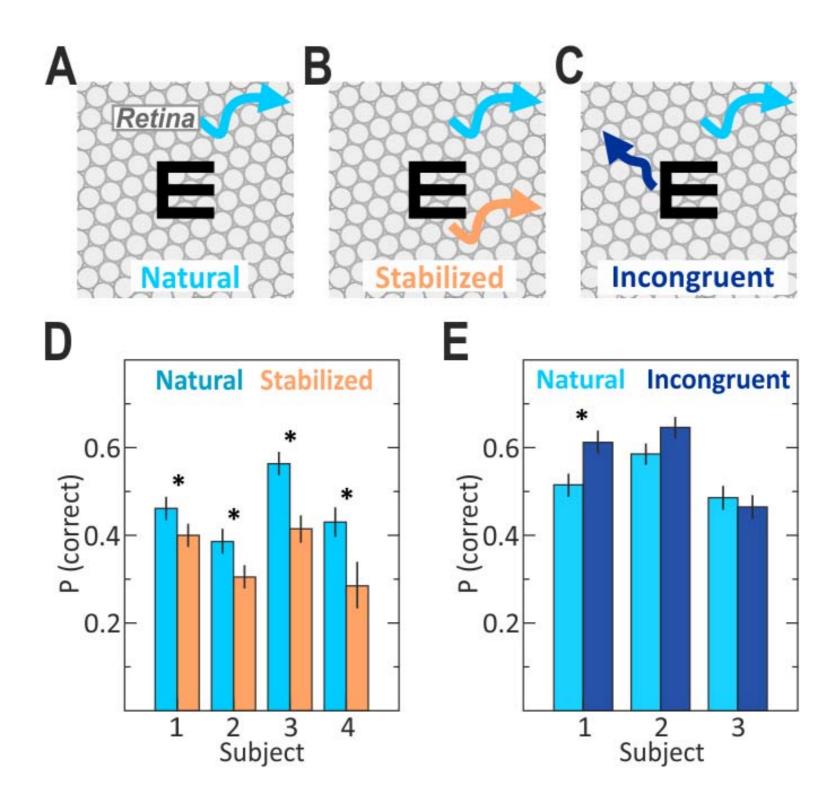
0.45

Sub-pixel Displacement

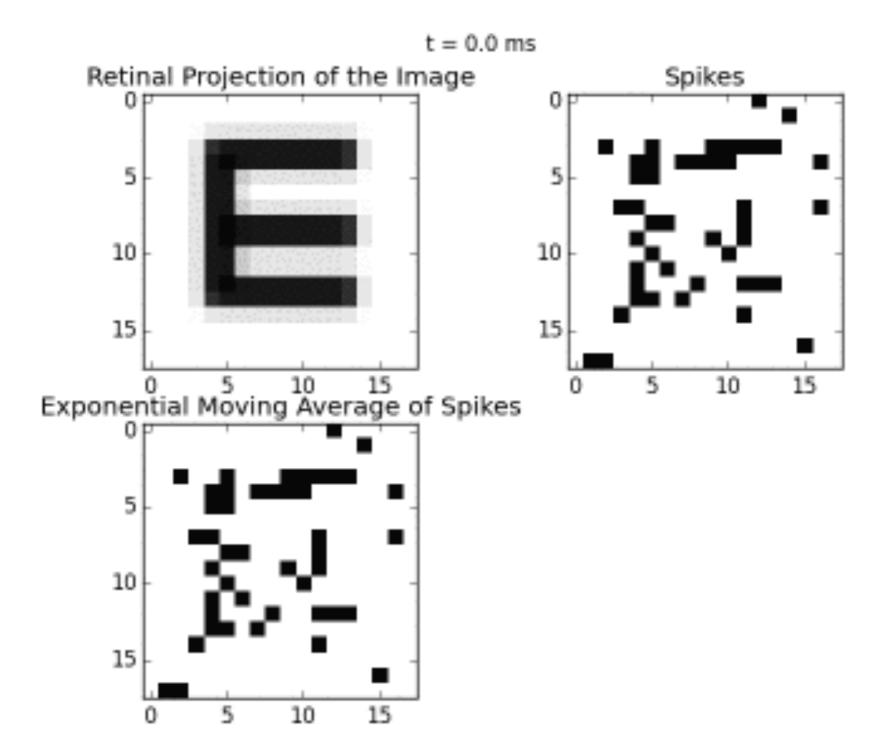
Kelly, Krainin, Liang, Levoy, Milanfar (2019)

## Retinal image motion helps pattern discrimination

(Ratnam, K., Domdei, N., Harmening, W. M., & Roorda, A., Journal of Vision, 2017)



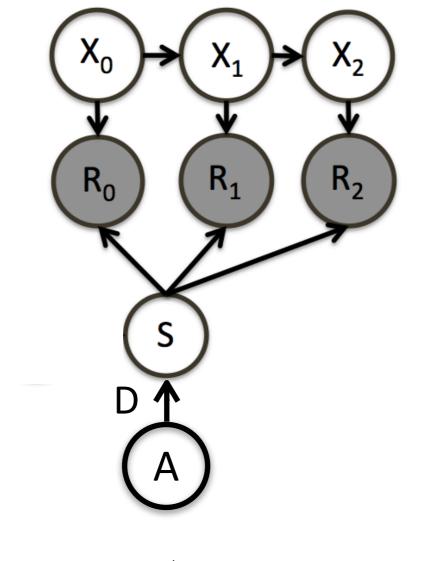
#### Simple averaging by cortex is not sufficient





Bayesian model for inferring form and motion (Anderson, Ratnam, Roorda & Olshausen, 2020)

Alex Anderson



#### **Eye position**

**Spikes** (from LGN afferents)

Pattern

S = DA

'Shape'

$$\hat{A} = \arg \max_{A} \log P(A|R)$$

#### Joint estimation of pattern (S) and position (X) from retinal spike trains (R) (Anderson, Ratnam, Roorda & Olshausen, 2020)

$$\hat{A} = \arg \max_{A} \log P(A|R)$$
  
=  $\arg \max_{A} \log P(R|A) P(A)$   
=  $\arg \max_{A} \log \sum_{X} P(R|X, S = DA) P(X) + \log P(A)$ 

$$\begin{split} & \hat{A} \ \leftarrow \ \arg\max_{A} \sum_{X} q(X) \ \log P(R|S = DA, X) + \log P(A) \\ & q(X) \ \leftarrow \ P(X|R, S = D\hat{A}) \end{split}$$

#### Joint estimation of pattern (S) and position (X) from retinal spike trains (R) (Anderson, Ratnam, Roorda & Olshausen, 2020)

Given current estimate of position  $(X_t)$ , update A

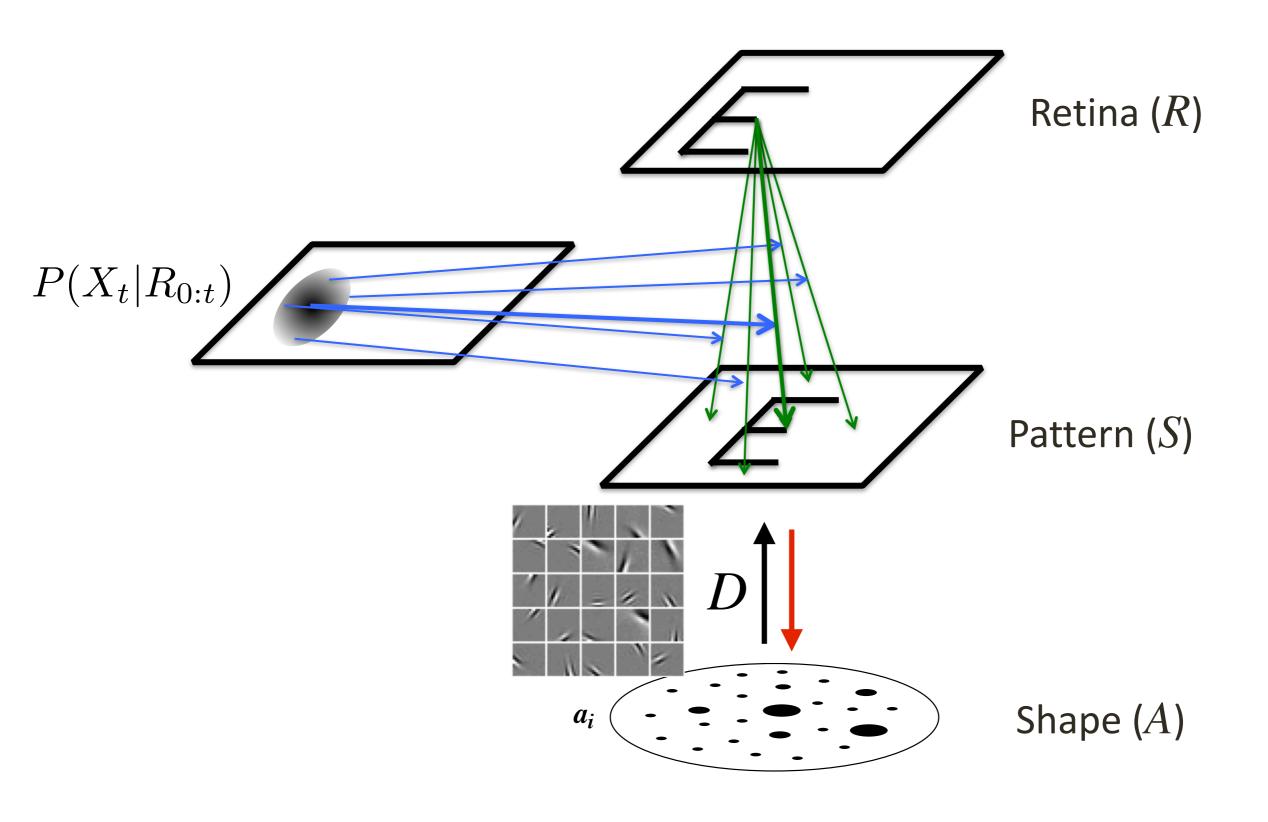
$$\hat{A}^{t+1} = \arg\max_{A} \sum_{t'=0}^{t} \sum_{j} \langle \log P(R_{j,t'} | X_{t'}, S = DA) \rangle_{P(X_{t'} | S^{t}, R_{0:t})} + \log P(A)$$

$$\log P(R_{j,t}|X_t, S) = R_{j,t} \log \lambda_j - \lambda_j dt$$
$$\log \lambda_j = \sum_{\vec{x}} g_j(\vec{x}) S(\vec{x} - \vec{X}_t)$$

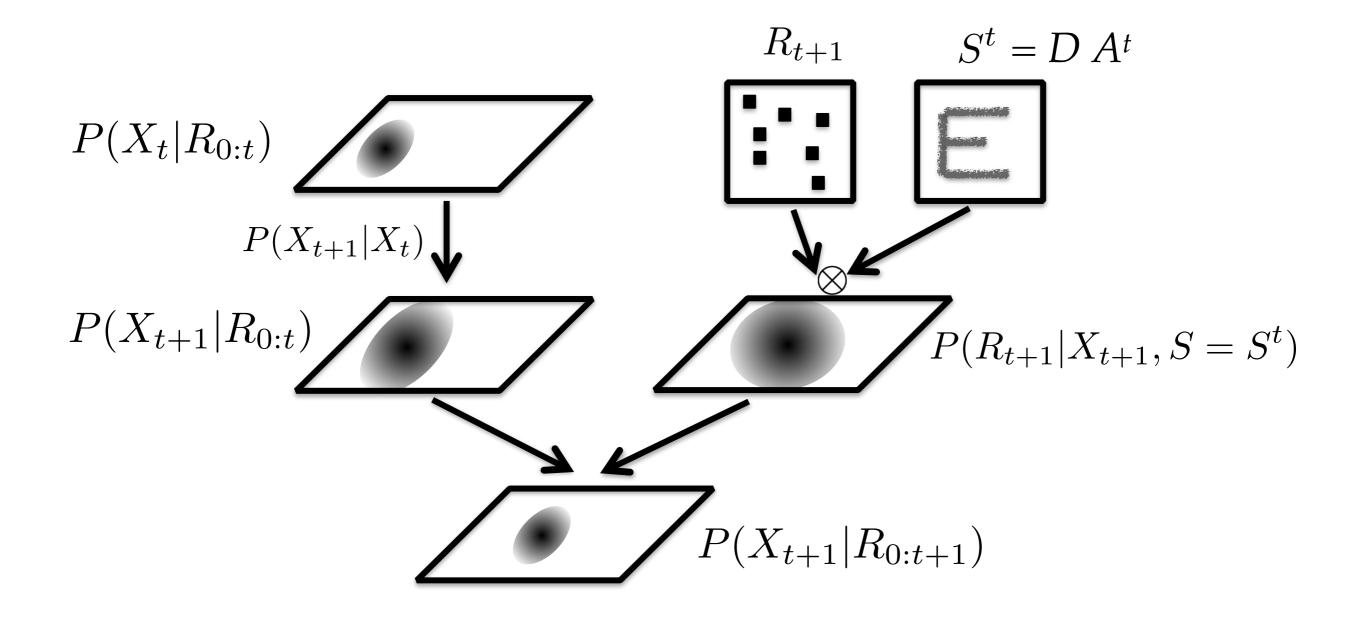
Given current estimate of shape ( $\hat{A}^t$ ), update X

$$P(X_t|S^t, R_{0:t}) \propto P(R_t|X_t, S^t = D\,\hat{A}^t) \sum_{X_{t-1}} P(X_t|X_{t-1}) P(X_{t-1}|S^{t-1}, R_{0:t-1})$$

## Given current estimate of position (X), update A

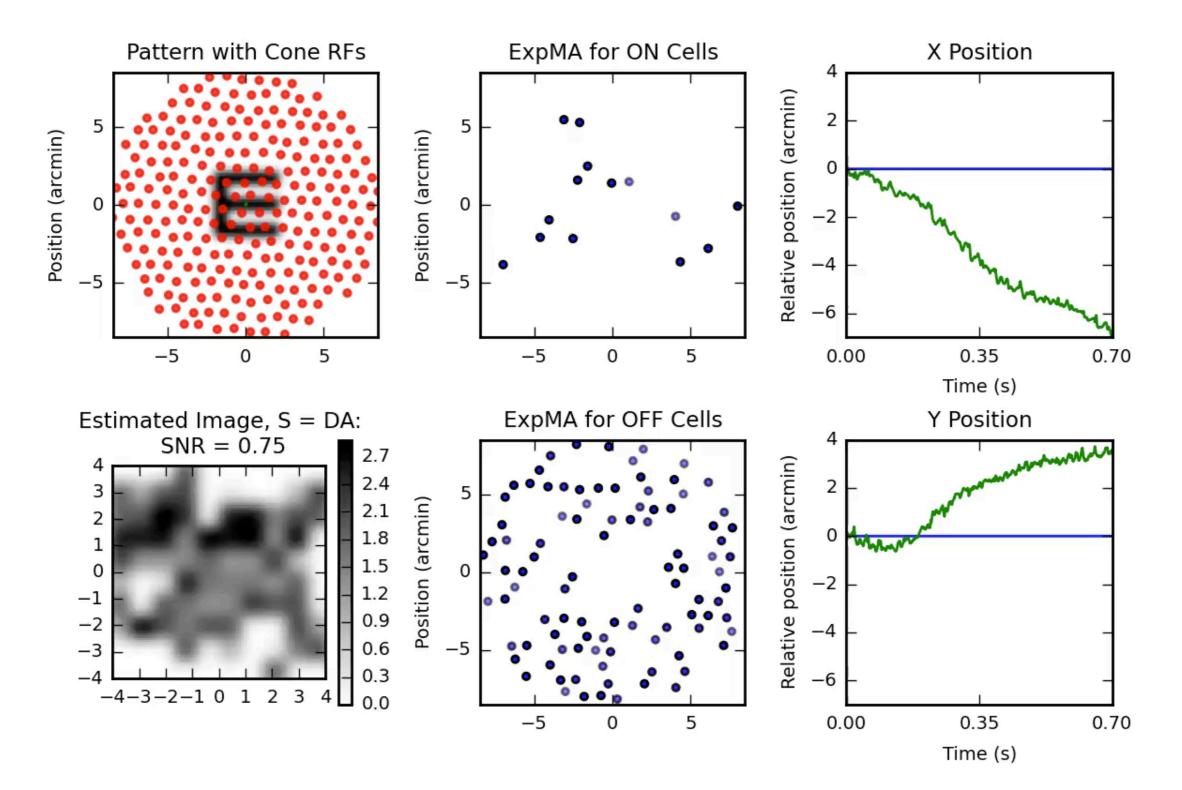


#### Given current estimate of pattern (A), update X

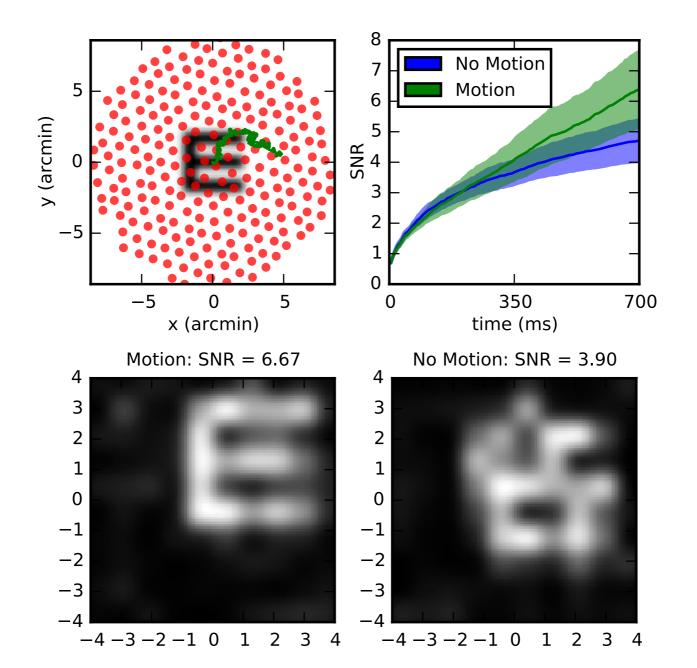


## Joint estimation of pattern (S) and position (X)

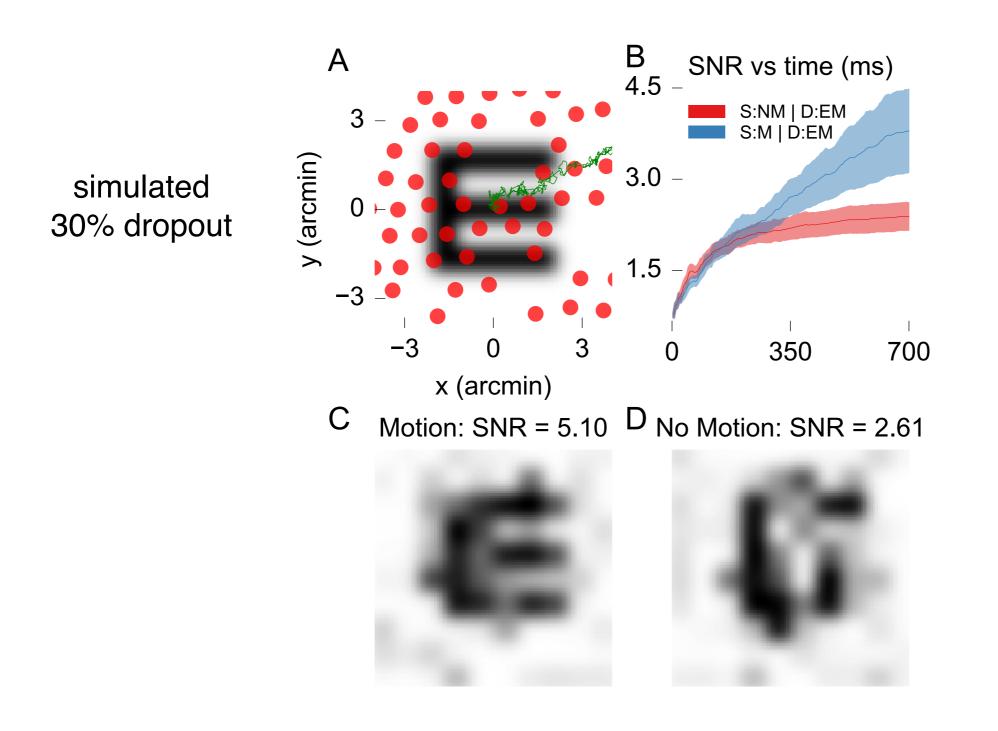




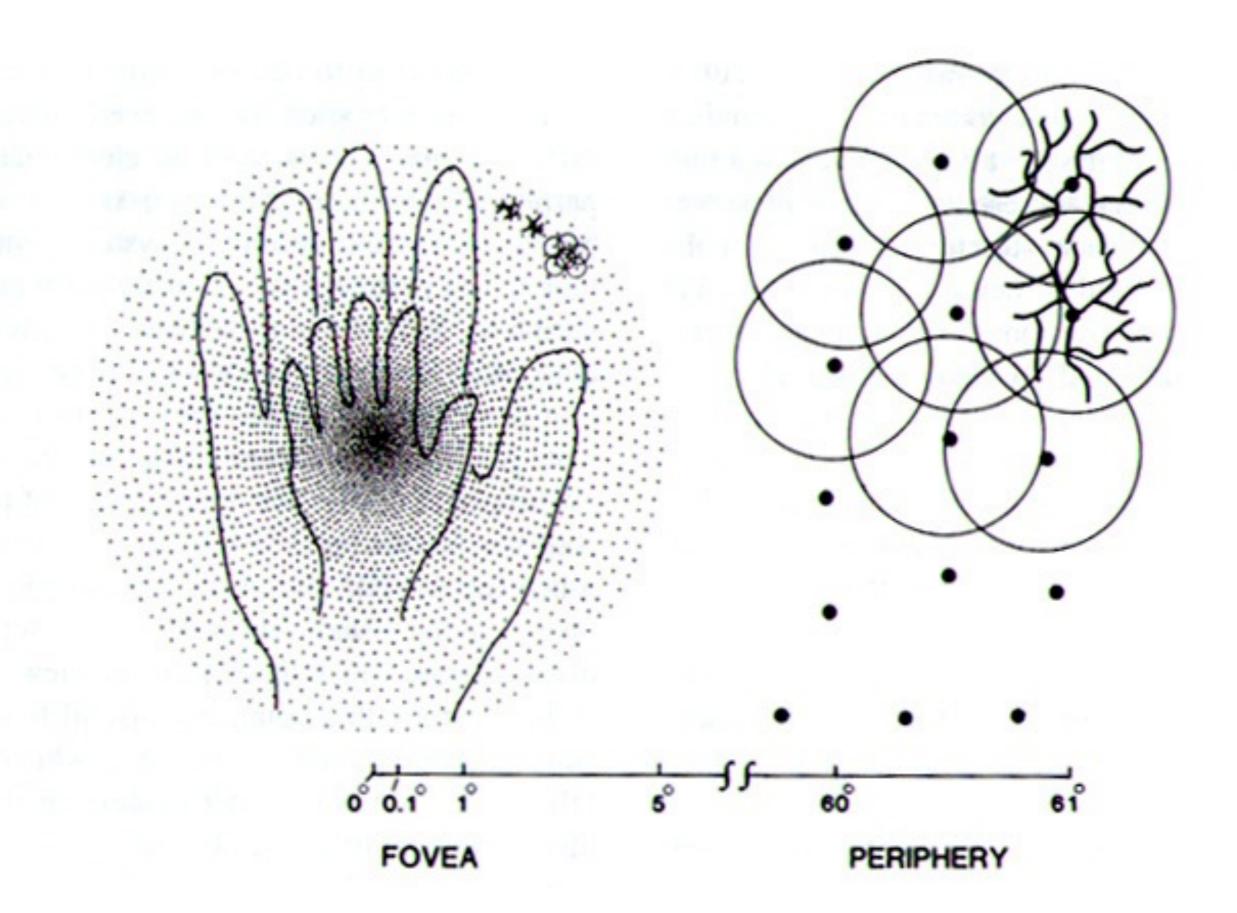
#### Motion <u>helps</u> estimation of pattern S



#### ...especially under conditions of cone loss.

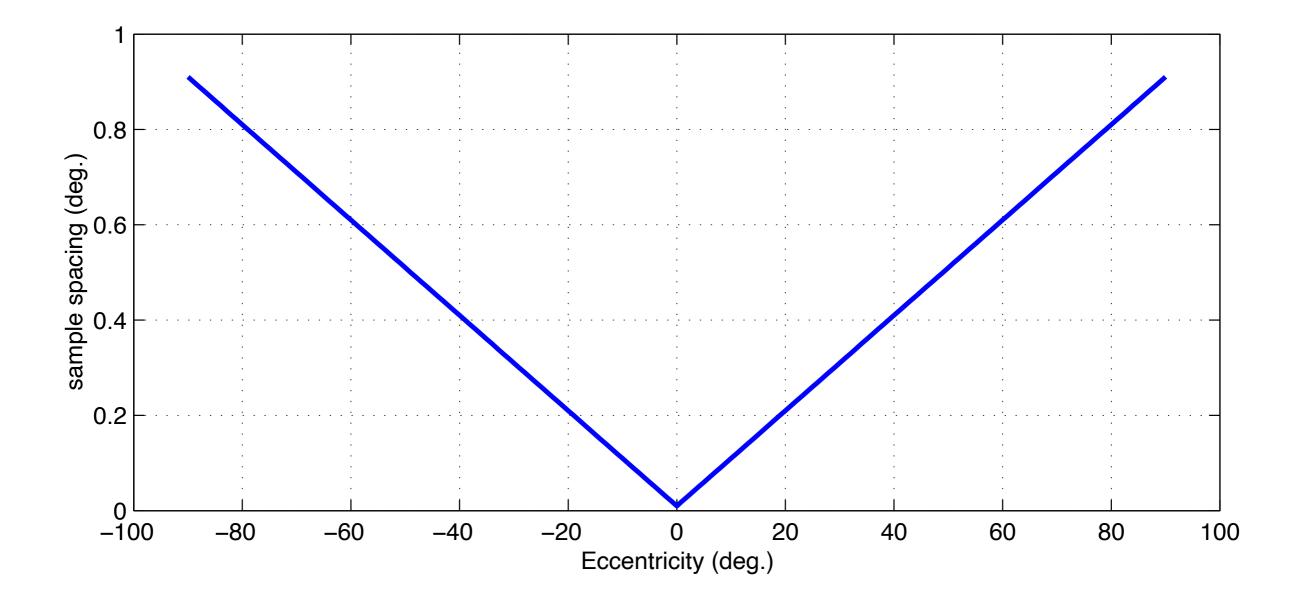


## Foveated sampling

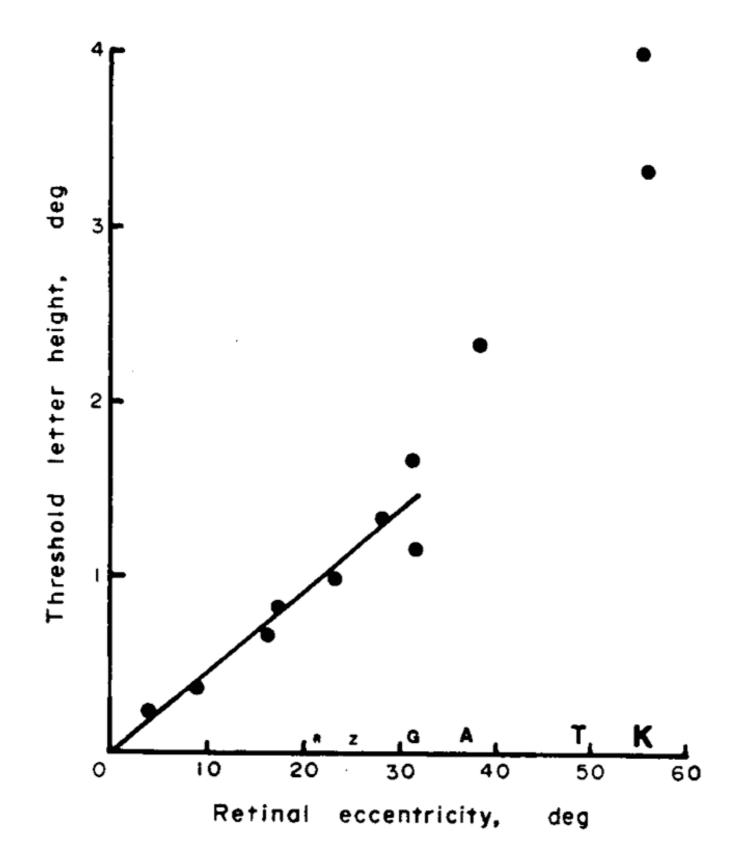


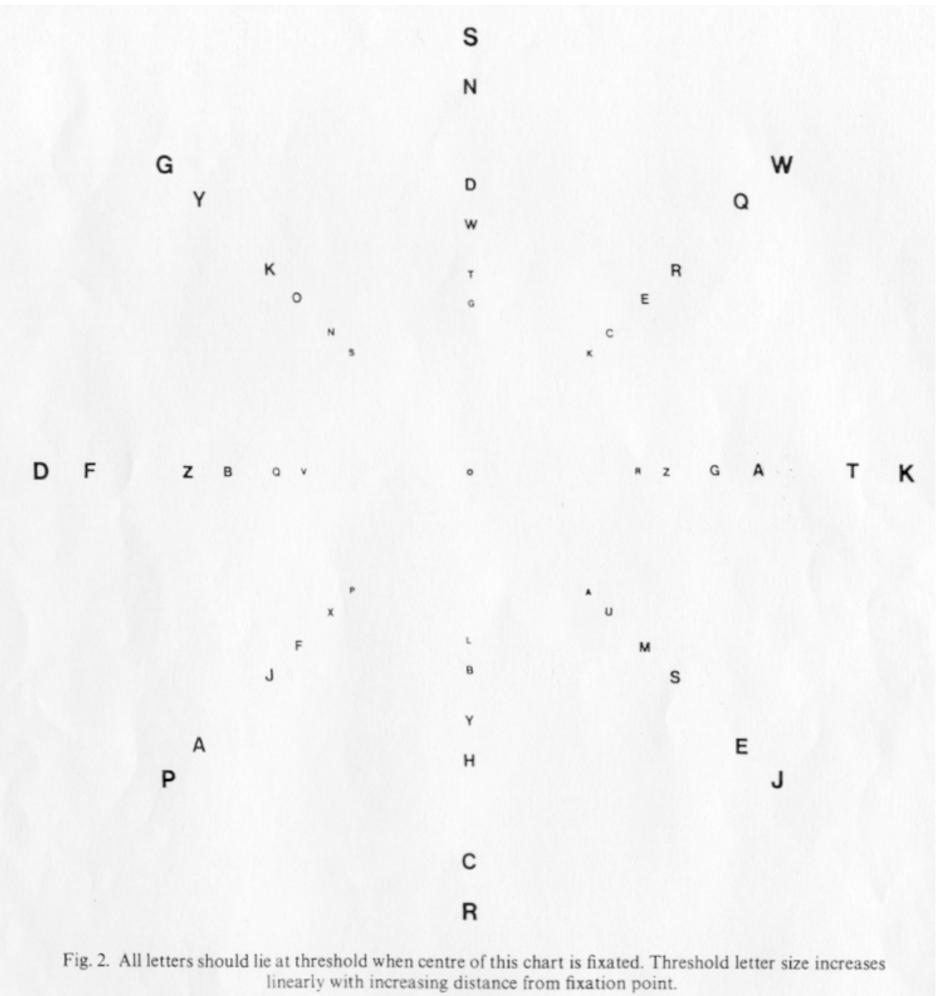
Retinal ganglion cell spacing as a function of eccentricity

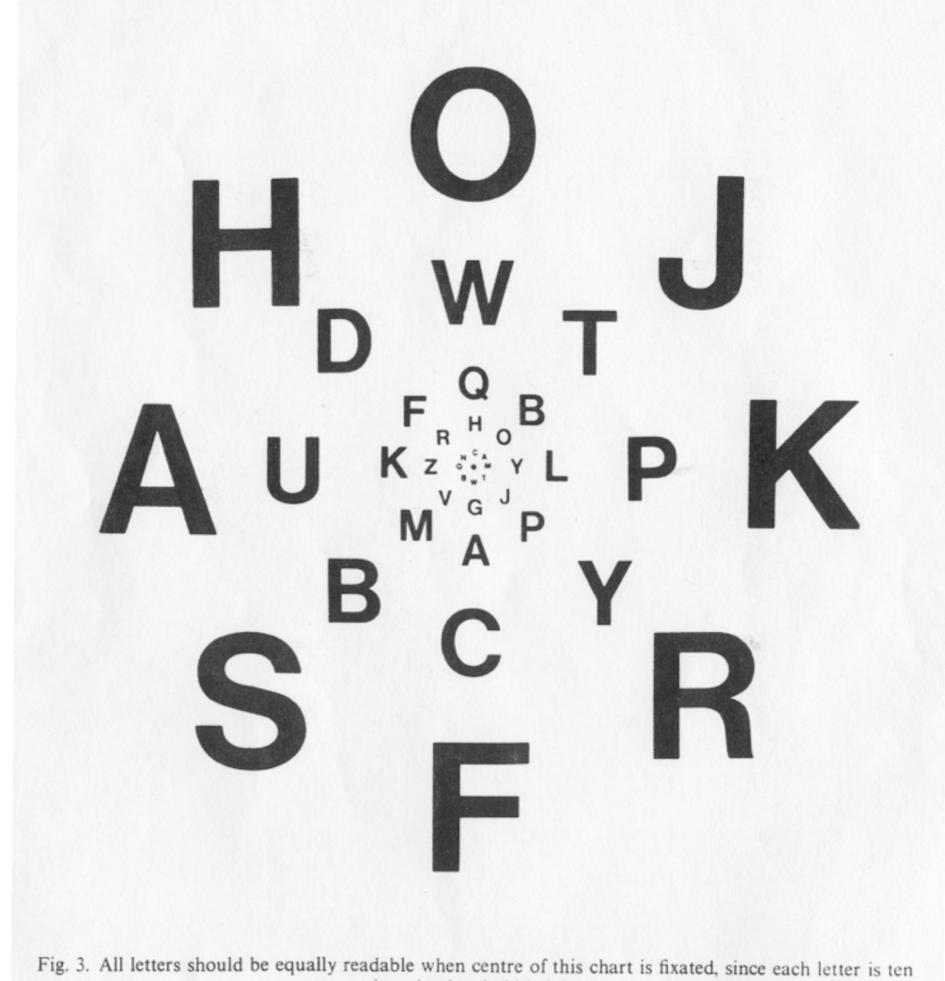
 $\Delta E \approx .01(|E|+1)$ 



## Letter size vs. eccentricity (Anstis, 1974)







times its threshold height.

#### A FOVEATED RETINA-LIKE SENSOR

#### USING CCD TECHNOLOGY

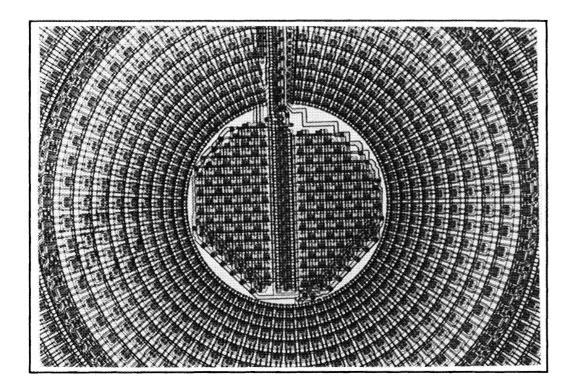
J. Van der Spiegel, G. Kreider Univ. of Pennsylvania, Dept. of Electrical Engineering Philadelphia, PA 19104-6390

> C. Claeys, I. Debusschere IMEC, Leuven, Belgium

G. Sandini University of Genova, DIST, Genova, Italy

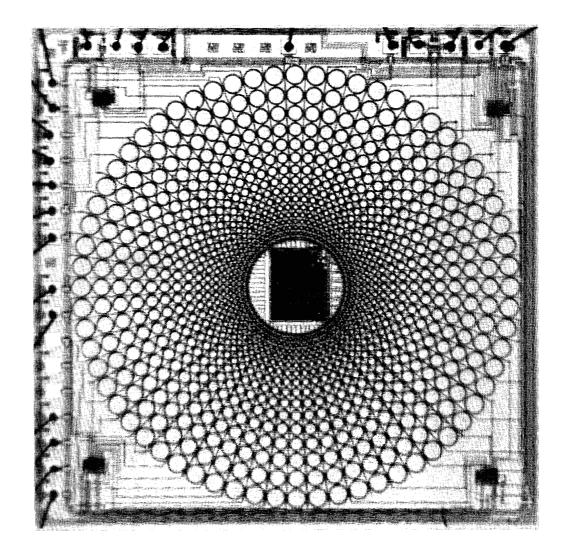
P. Dario, F. Fantini Scuola Superiore S. Anna, Pisa, Italy

> P. Bellutti, G. Soncini IRST, Trento, Italy

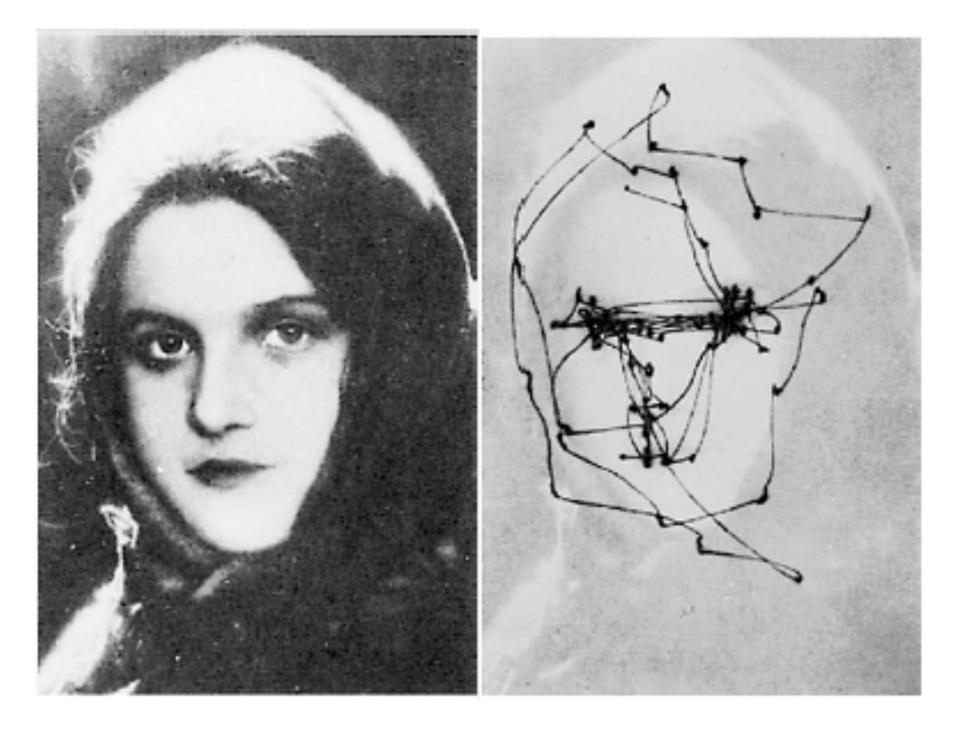


#### A Foveated Image Sensor in Standard CMOS Technology

Robert Wodnicki, Gordon W. Roberts, Martin D. Levine Department of Electrical Engineering, McGill University, Montréal, Québec, CANADA, H3A 2A7



#### Human eye movements during viewing of an image



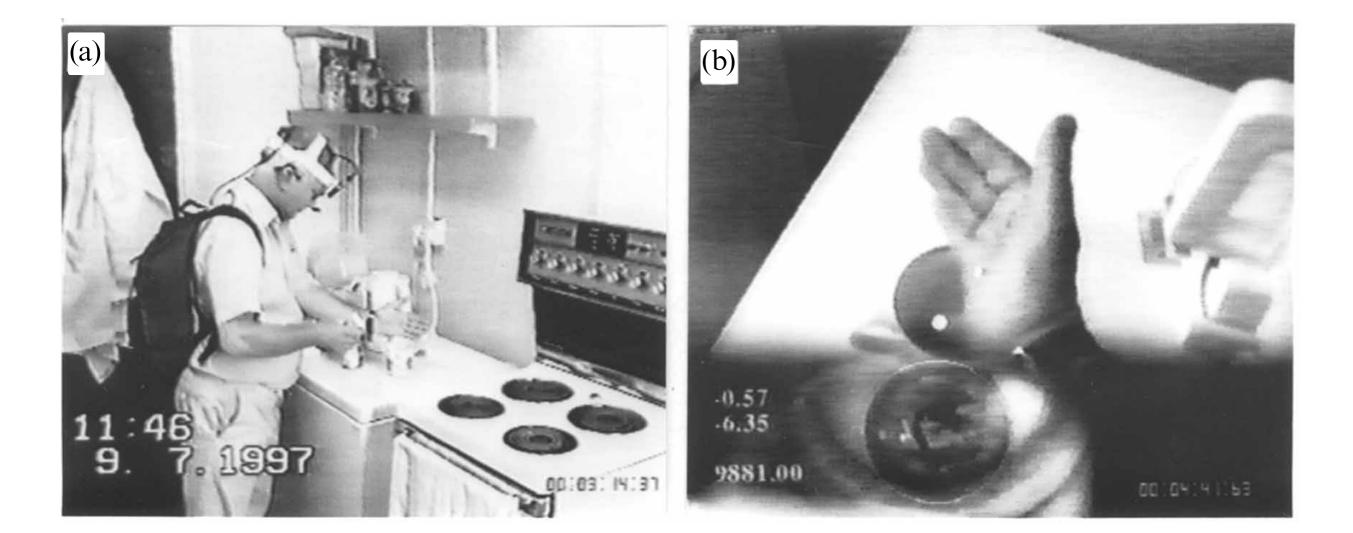
Yarbus (1967)

DOI:10.1068/p2935

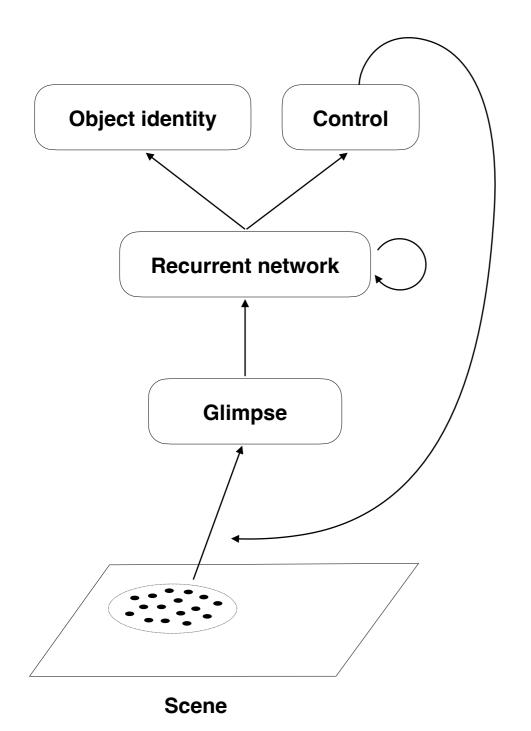
## The roles of vision and eye movements in the control of activities of daily living

#### Michael Land, Neil Mennie, Jennifer Rusted

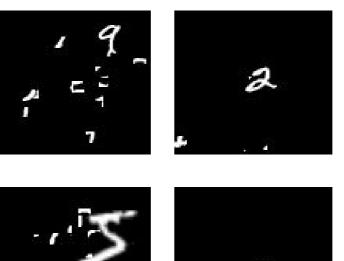
Sussex Centre for Neuroscience and Laboratory of Experimental Psychology, School of Biological Sciences, University of Sussex, Brighton BN1 9QG, UK; e-mail: M.F.Land@sussex.ac.uk Received 4 May 1999, in revised form 9 August 1999



#### Learning the glimpse window sampling array (Cheung, Weiss & Olshausen, 2017)



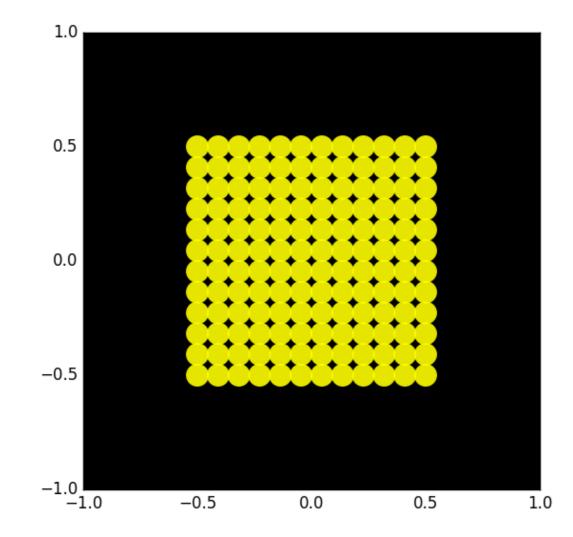
- Network is trained to correctly classify the digit in the scene.
- To do this it must find a digit and move its glimpse window to that location.



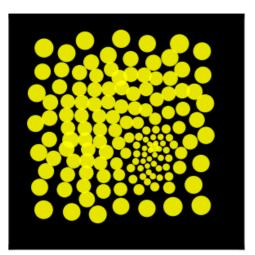


Example MNIST scenes

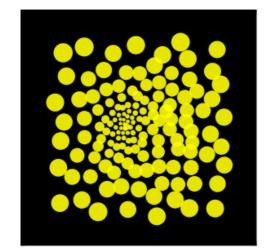
#### Evolution of the sampling array during training



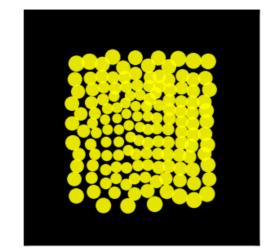
## Learned sampling arrays for different conditions



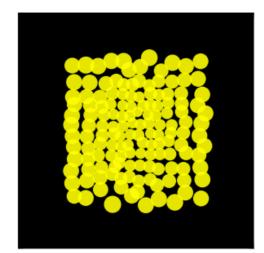
Translation only (Dataset 1)



Translation only (Dataset 2)

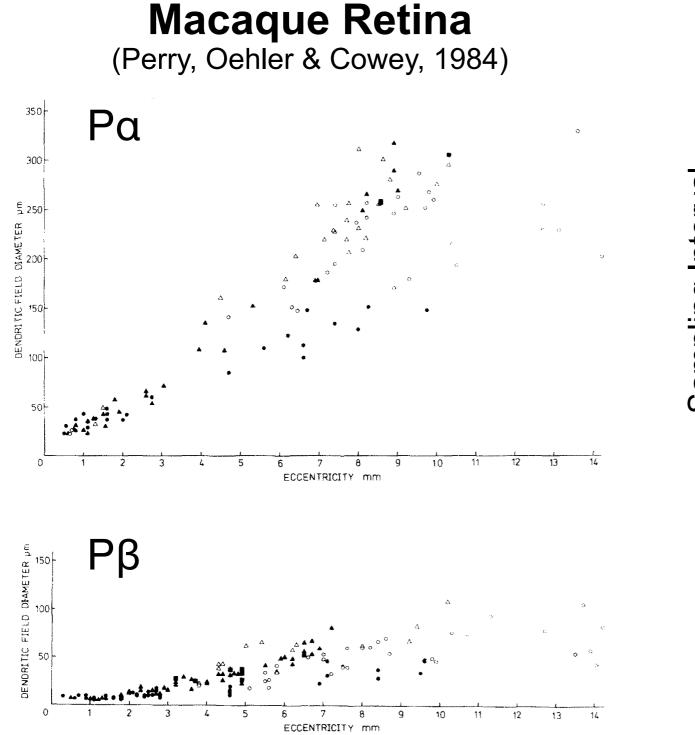


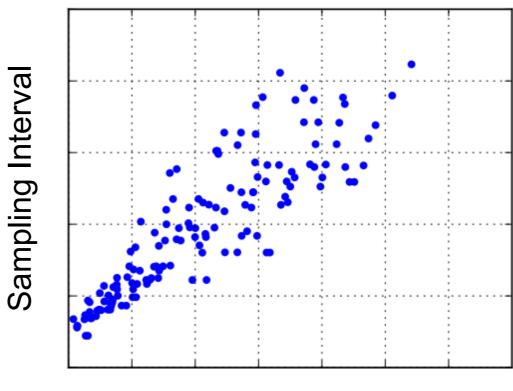
Translation & zoom (Dataset 1)



Translation & zoom (Dataset 2)

#### Comparison to primate retina





**Model** 

Eccentricity

#### Comparison to primate retina

