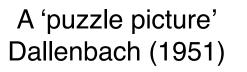
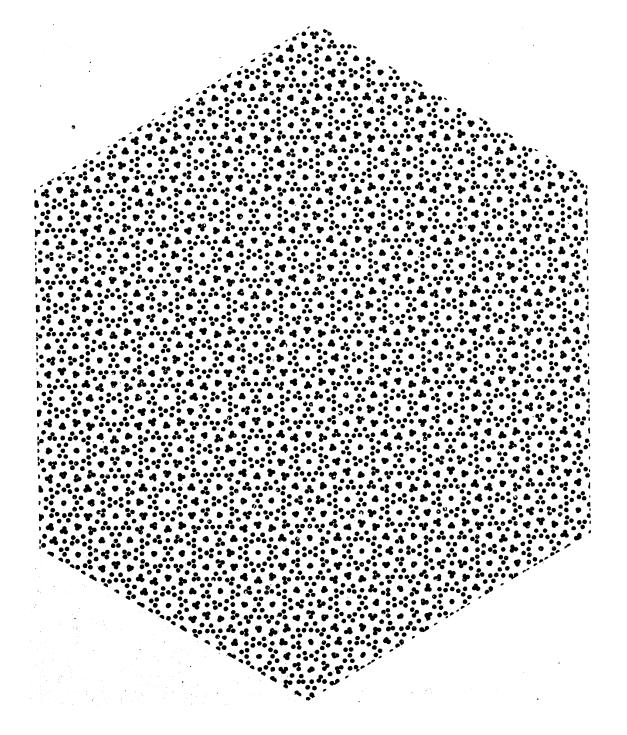
Attractor neural networks



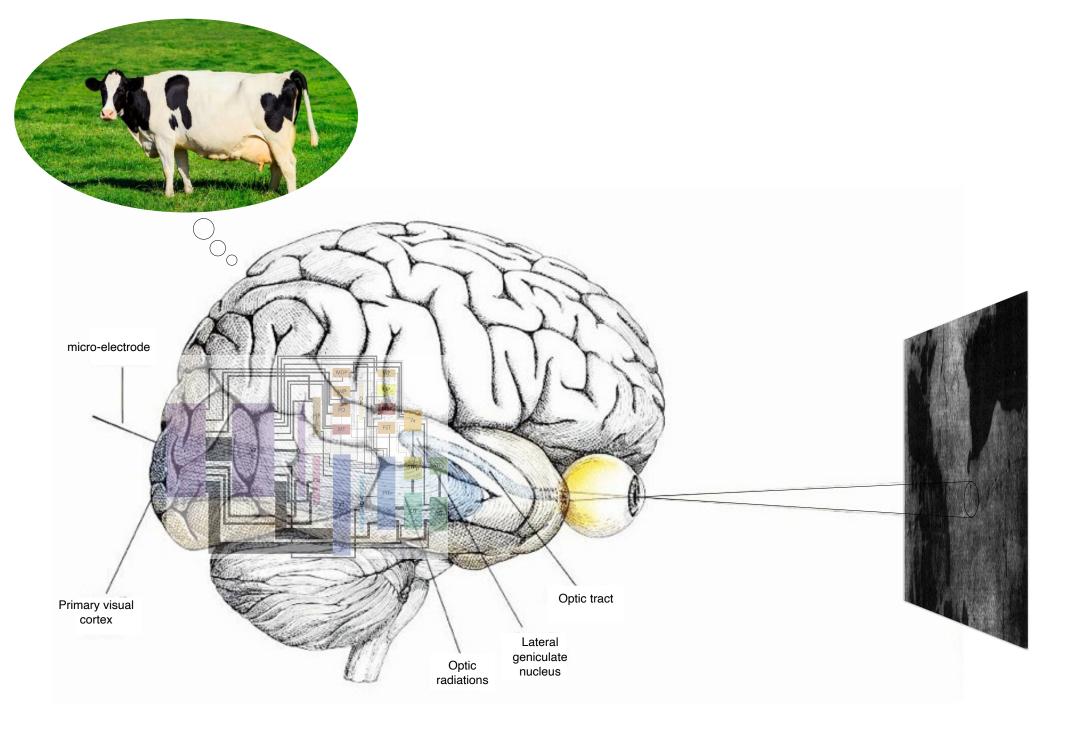




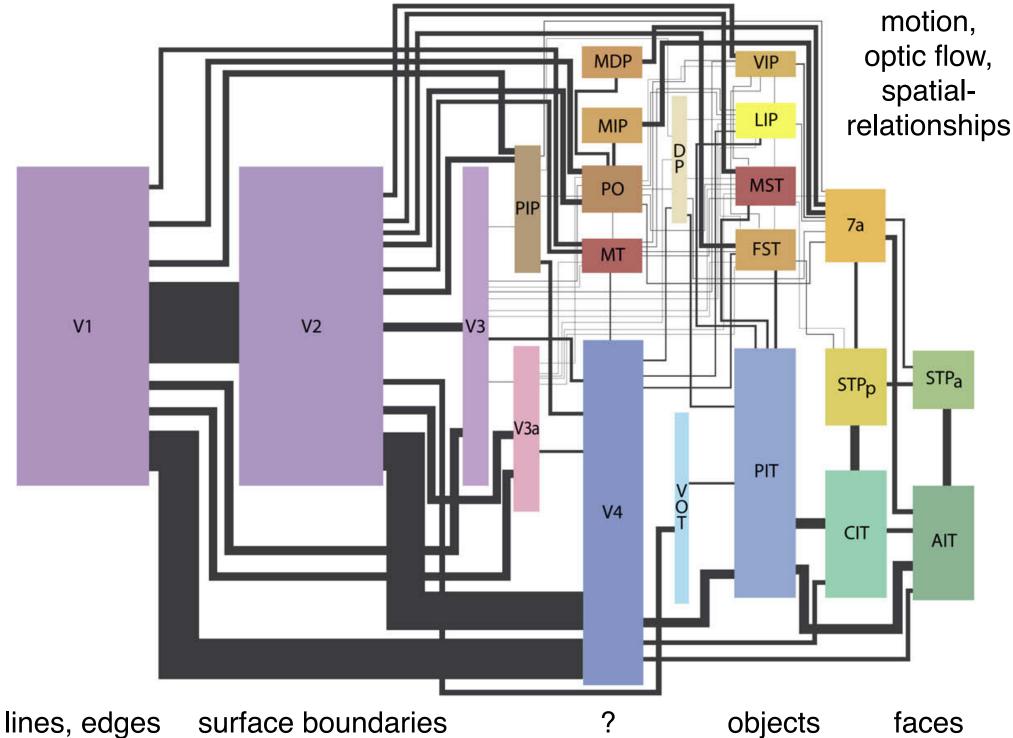
from Marroquin (1976)

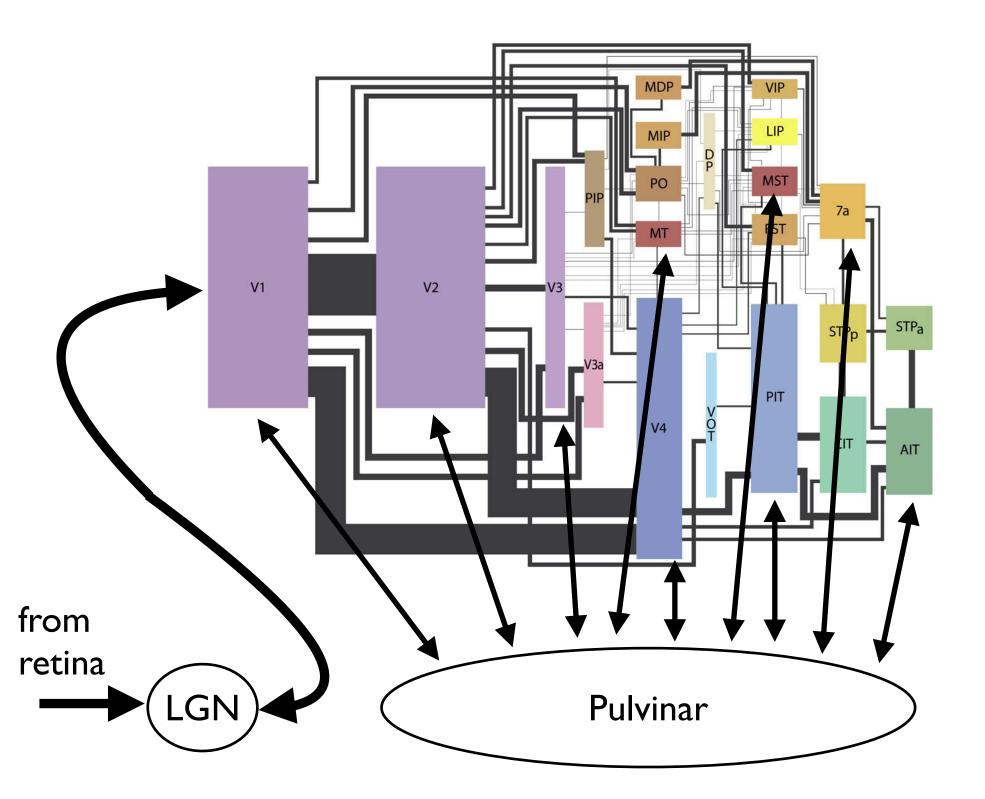
Andy Goldsworthy artwork



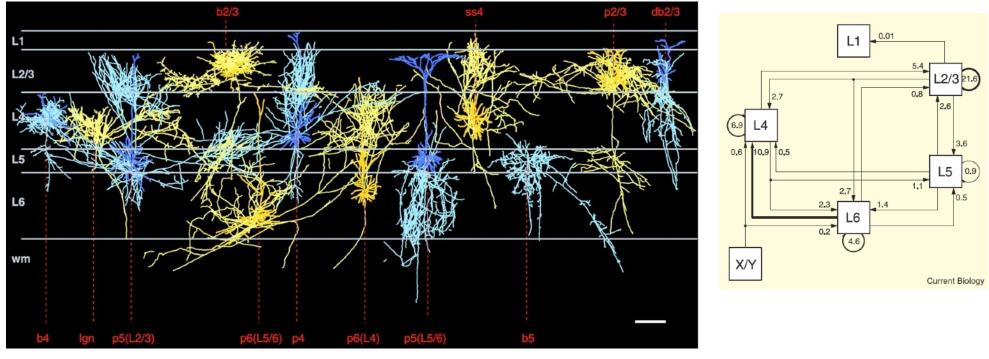


Wallisch & Movshon (2008)



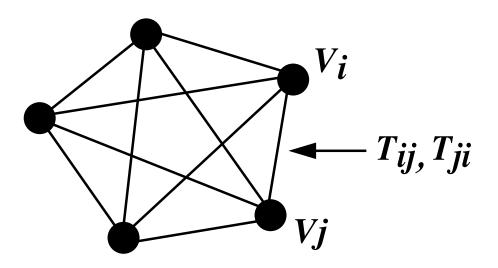


Recurrent neuronal circuits in the neocortex (Douglas & Martin 2007)



(Binzegger, Douglas & Martin, 2004)

(Douglas and Martin, 2007)



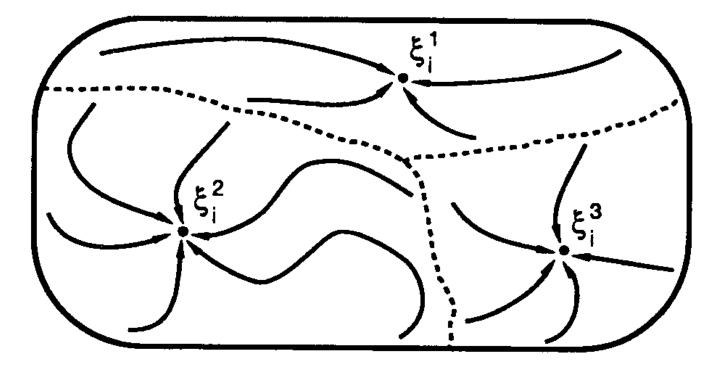
$$U_i = \sum_j T_{ij} V_j$$
$$V_i = \operatorname{sign}(U_i)$$

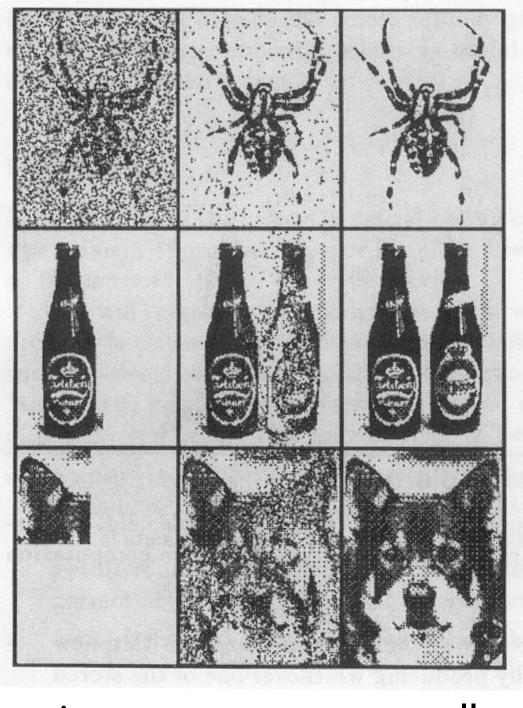
Dynamics:

Energy function:

$$E = -\frac{1}{2} \sum_{i,j \neq i} T_{ij} V_i V_j$$

Basins of attraction





→ recall input

Outer-product (Hebb) rule

$$T_{ij} = \sum_{\alpha} P_i^{(\alpha)} P_j^{(\alpha)}$$

= $P_i^{(1)} P_j^{(1)} + P_i^{(2)} P_j^{(2)} + P_i^{(3)} P_j^{(3)} + \dots$

or
$$\mathbf{T} = \mathbf{P}^{(1)} \mathbf{P}^{(1)}^T + \mathbf{P}^{(2)} \mathbf{P}^{(2)}^T + \mathbf{P}^{(3)} \mathbf{P}^{(3)}^T + \dots$$

Thus

$$\mathbf{U} \cong (\mathbf{P}^{(1)} \mathbf{P}^{(1)^{T}} + \mathbf{P}^{(2)} \mathbf{P}^{(2)^{T}} + \mathbf{P}^{(3)} \mathbf{P}^{(3)^{T}} + \dots) \mathbf{V}$$

= $\mathbf{P}^{(1)} (\mathbf{P}^{(1)} \cdot \mathbf{V}) + \mathbf{P}^{(2)} (\mathbf{P}^{(2)} \cdot \mathbf{V}) + \mathbf{P}^{(3)} (\mathbf{P}^{(3)} \cdot \mathbf{V}) + \dots$
 $\mathbf{V} = \operatorname{sgn}(\mathbf{U})$

Capacity vs. error rate

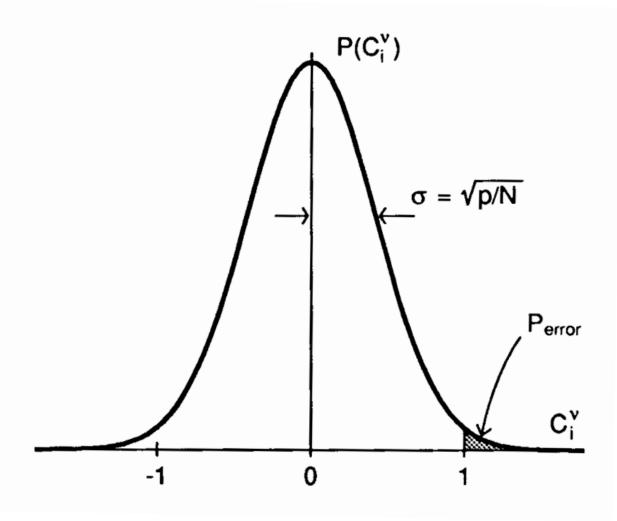
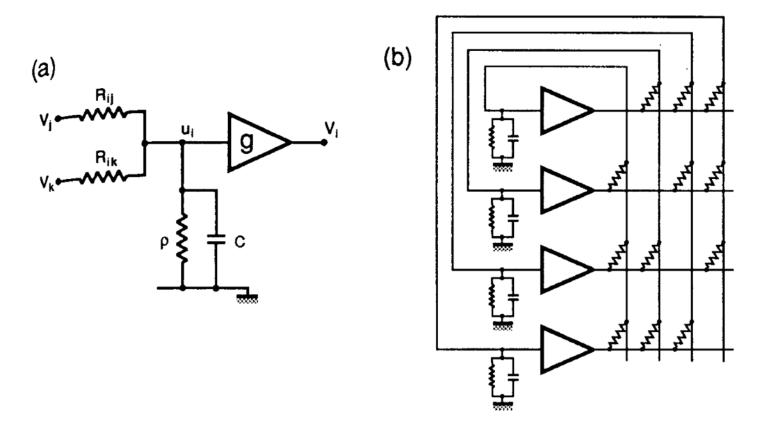


TABLE 2.1 Capacities

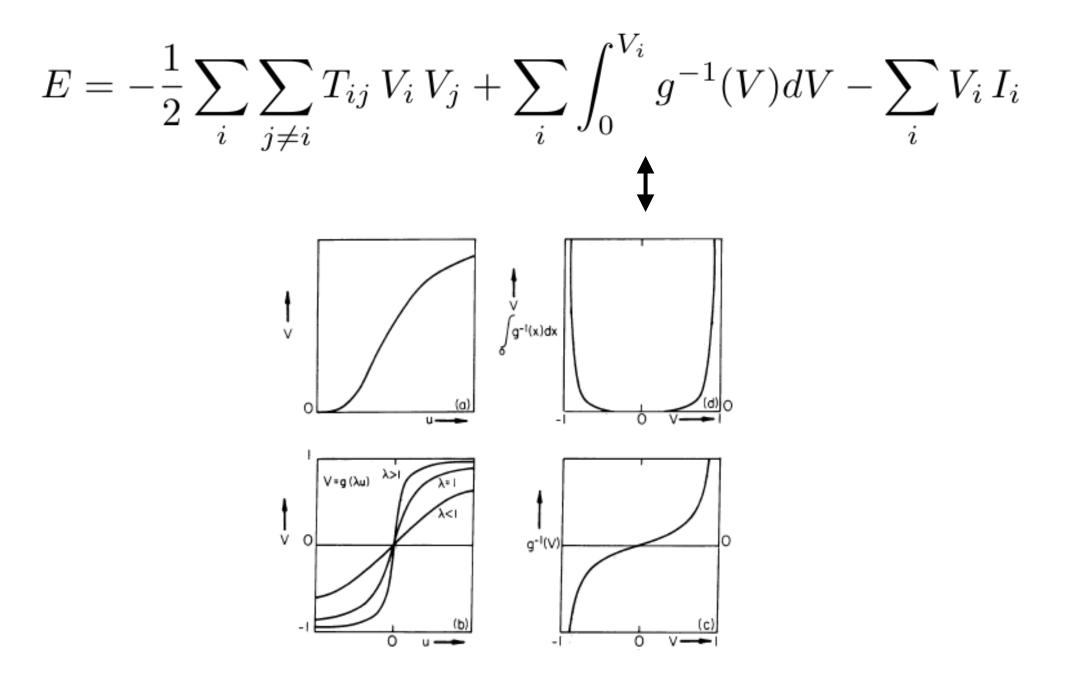
	•
$P_{\rm error}$	p_{\max}/N
0.001	0.105
0.0036	0.138
0.01	0.185
0.05	0.37
0.1	0.61

Hopfield network with analog units



$$\tau \, \dot{u}_i + u_i = \sum_{j \neq i} T_{ij} \, V_j + I_i$$
$$V_i = g(u_i)$$

Lyapunov function



From Lyapunov function to dynamics

$$E = -\frac{1}{2} \sum_{i} \sum_{j \neq i} T_{ij} V_i V_j + \sum_{i} \int_0^{V_i} g^{-1}(V) dV - \sum_{i} V_i I_i$$

τ 7

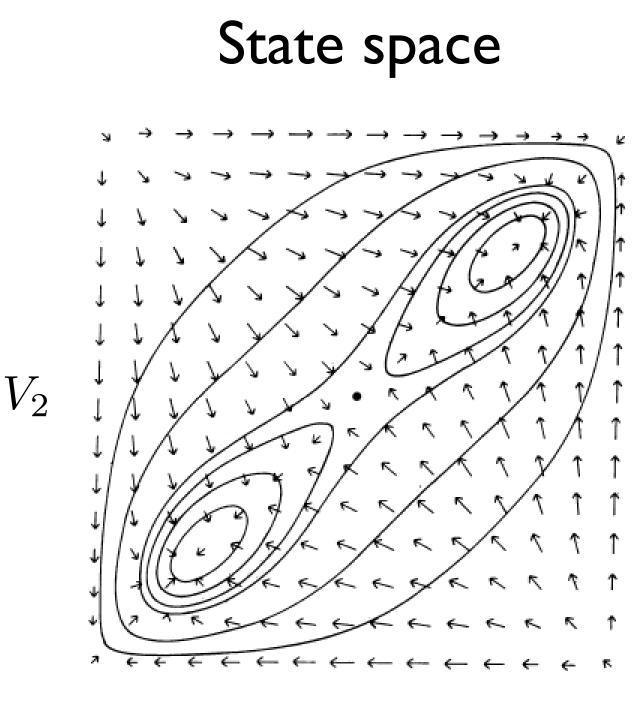
$$\frac{\partial E}{\partial V_k} = -\sum_{j \neq k} T_{kj} V_j + g^{-1}(V_k) - I_k$$

 0π

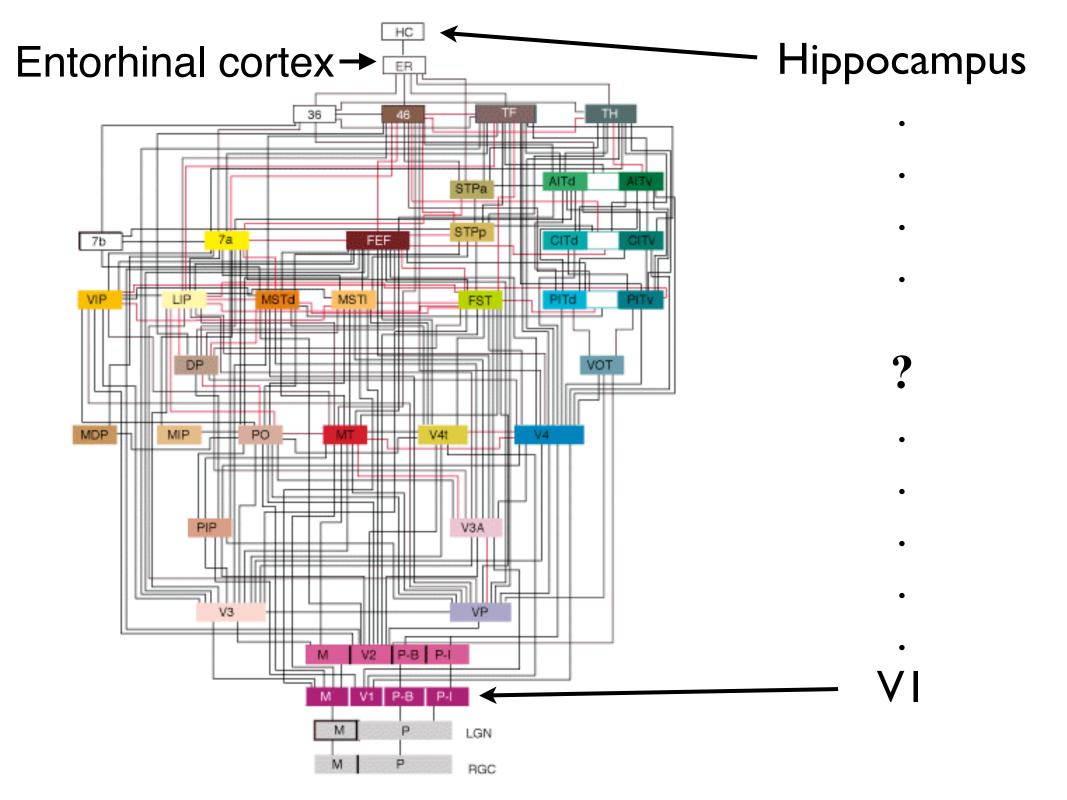
Let
$$u_i = g^{-1}(V_i) \Rightarrow V_i = g(u_i)$$

 $\dot{u}_i \propto -\frac{\partial E}{\partial V_i} = \sum_{j \neq i} T_{ij} V_j + I_i - u_i$

Thus $\dot{E} = \frac{\partial E}{\partial V} \frac{\partial V}{\partial u} \dot{u} < 0$



 V_1



Place cells, grid cells, head-direction cells and continuous attractor neural networks

