

Analogical Reasoning with VSAs/HD computing

What is an analogy?

“Analogies are partial similarities between different situations that support further inference”

--Dedre Gentner

“...the very blue that fills the whole sky of cognition--analogy is *everything*, or very nearly so, in my view.”

--Douglas Hofstadter

What is an analogy?

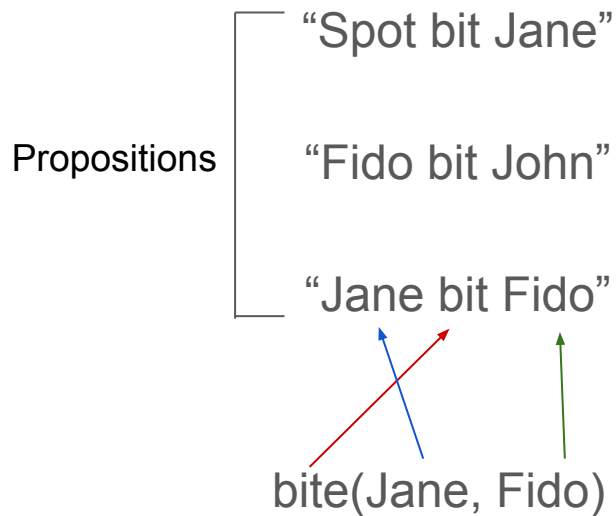
“Spot bit Jane”

“Fido bit John”

“Jane bit Fido”

...an analogy captures *correspondences* between each of these instances

What is an analogy?



`predicate(agent, object)`

What is an analogy?

Four (give or take) tasks of *analogical reasoning*.

1. Retrieval

- Accessing analogous instances from memory--unconscious and fast.

2. Judgement

- Estimating the *similarity* of different instances based on structural and semantic properties.
Conscious and slow.

3. Mapping

- Finding *structural correspondences* between instances

4. Inference

- Applying structure from one instance to a generate or explain a novel instance


Propositional analogies with HRRs

- Encoding depends on the analogical reasoning task
- Example (from Tony Plate):
 - HRRs encodings that reflect human judgements of similarity

Propositional analogies with HRRs

“Spot bit Jane, causing Jane to flee from Spot”

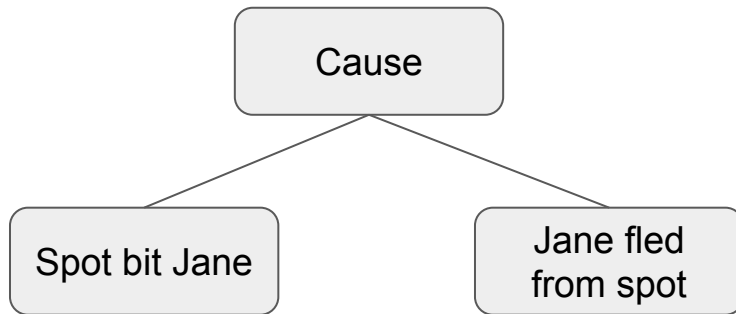

$$\mathbf{P}_{\text{bite}} = \mathbf{bite} + \mathbf{spot} + \mathbf{jane} + \mathbf{bite}_{\text{agt}} \otimes \mathbf{spot} \\ + \mathbf{bite}_{\text{obj}} \otimes \mathbf{jane}$$


$$\mathbf{P}_{\text{flee}} = \mathbf{flee} + \mathbf{spot} + \mathbf{jane} + \mathbf{flee}_{\text{agt}} \otimes \mathbf{jane} \\ + \mathbf{flee}_{\text{from}} \otimes \mathbf{spot}$$

$$\mathbf{P} = \mathbf{cause} + \mathbf{P}_{\text{bite}} + \mathbf{P}_{\text{flee}} + \mathbf{cause}_{\text{antc}} \otimes \mathbf{P}_{\text{bite}} \\ + \mathbf{cause}_{\text{cnsq}} \otimes \mathbf{P}_{\text{flee}}$$

Propositional analogies with HRRs

“Spot bit Jane, causing Jane to flee from Spot”



Propositional analogies with HRRs

Different types of “similarity”

- LS (literal similarity): ‘Fido bit John, causing John to flee from Fido’. (Has both structural and superficial similarity to the probe **P**.)
- SF (surface features): ‘John fled from Fido, causing Fido to bite John’. (Has superficial but not structural

$$LS > CM \geq SF > AN \geq FOR$$

superficial similarity, but types of corresponding objects are switched.)

- AN (analogy): ‘Mort bit Felix, causing Felix to flee from Mort’. (Has structural but not superficial similarity.)
- FOR (first-order relations only): ‘Mort fled from Felix, causing Felix to bite Mort’. (Has neither structural nor superficial similarity, other than shared predicates.)

Propositional analogies with HRRs

Table 2

<i>Episodes in long-term memory</i>		<i>Commonalities with probe</i>			<i>Similarity scores</i>	
					<i>HRR</i>	<i>MAC</i>
E_{LS}	Fido bit John, causing John to flee from Fido	✓	✓	✓	0.71	1.0
E_{SF}	John fled from Fido, causing Fido to bite John	✓	✓	×	0.47	1.0
E_{CM}	Fred bit Rover, causing Rover to flee from Fred	✓	✓	✓	0.47	1.0
E_{AN}	Mort bit Felix, causing Felix to flee from Mort	×	✓	✓	0.42	0.6
E_{FOR}	Mort fled from Felix, causing Felix to bite Mort	×	✓	×	0.30	0.6

P, Spot bit Jane, causing Jane to flee from Spot.

Issues with what we've shown so far

- Complicated
- Hand-designed
- How do atomic concepts (vectors) get their meaning?
- Evaluated similarity without further decomposition

Simplifying things

$$A : B :: C : D$$

Simplifying things

Bit Bit
“Spot” : “Jane” : : “Fido” : “John”

Simplifying things

$$A : B :: C : D$$

Visual Analogies

Scene A



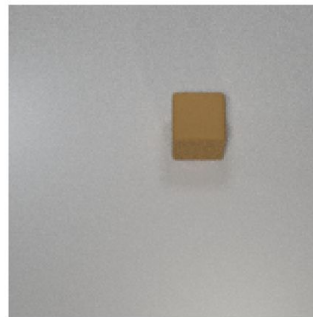
Scene B



Scene C



Scene D

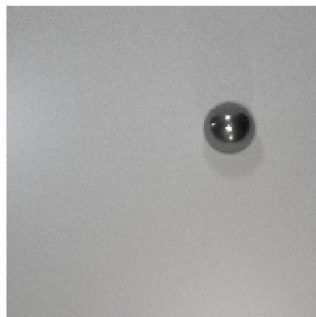


Visual Analogies

Scene A



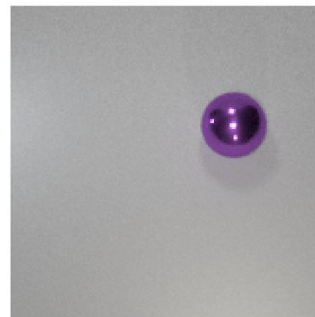
Scene B



Scene C

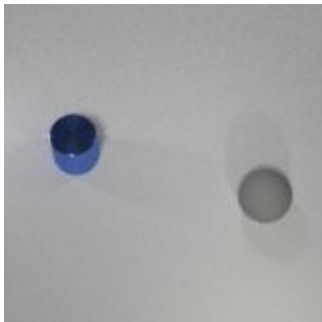


Scene D

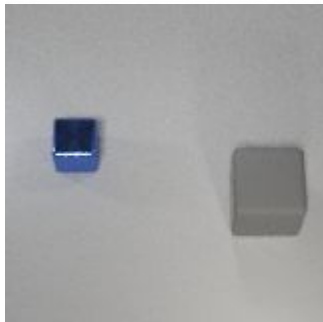


Visual Analogies

Scene A



Scene B



Scene C



Scene D



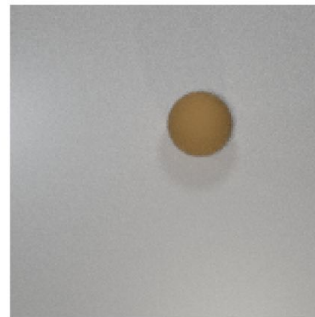
Scene A



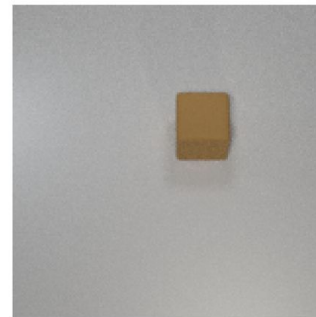
Scene B



Scene C



Scene D



A : B

C : D

A \sim BLUE \otimes METAL \otimes SPHERE $:= S_A$

B \sim BLUE \otimes METAL \otimes CUBE $:= S_B$

C \sim BROWN \otimes RUBBER \otimes SPHERE $:= S_C$

D \sim BROWN \otimes RUBBER \otimes CUBE $:= S_D$

Representing relations with bind/unbinding

$$A : B \sim S_A^{-1} \otimes S_B = \text{SPHERE}^{-1} \otimes \text{CUBE}$$

$$C : D \sim S_C^{-1} \otimes S_D = \text{SPHERE}^{-1} \otimes \text{CUBE}$$

$$S_A^{-1} \otimes S_B \otimes S_C = S_D$$

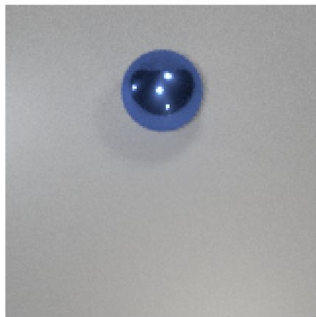
$$A \sim \text{BLUE} \otimes \text{METAL} \otimes \text{SPHERE} := S_A$$

$$B \sim \text{BLUE} \otimes \text{METAL} \otimes \text{CUBE} := S_B$$

$$C \sim \text{BROWN} \otimes \text{RUBBER} \otimes \text{SPHERE} := S_C$$

$$D \sim \text{BROWN} \otimes \text{RUBBER} \otimes \text{CUBE} := S_D$$

Scene A



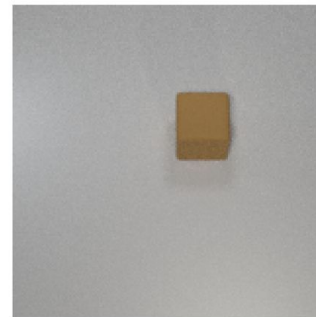
Scene B



Scene C



Scene D



A : B

C : D

$A \sim \text{COLOR} \otimes \text{BLUE} + \text{MATERIAL} \otimes \text{METAL} + \text{SHAPE} \otimes \text{SPHERE} := S_A$

$B \sim \text{COLOR} \otimes \text{BLUE} + \text{MATERIAL} \otimes \text{METAL} + \text{SHAPE} \otimes \text{CUBE} := S_B$

$C \sim \text{COLOR} \otimes \text{BROWN} + \text{MATERIAL} \otimes \text{RUBBER} + \text{SHAPE} \otimes \text{SPHERE} := S_C$

$D \sim \text{COLOR} \otimes \text{BROWN} + \text{MATERIAL} \otimes \text{RUBBER} + \text{SHAPE} \otimes \text{CUBE} := S_D$

Representing relations with addition/subtraction

$$A : B \sim S_B - S_A = \text{SHAPE} \otimes (\text{CUBE} - \text{SPHERE})$$

$$C : D \sim S_D - S_C = \text{SHAPE} \otimes (\text{CUBE} - \text{SPHERE})$$

$$S_C + S_B - S_A = S_D$$

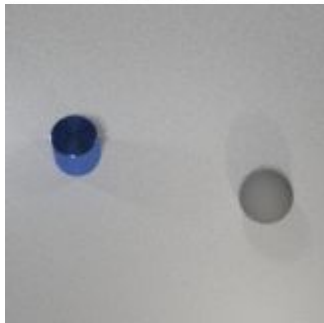
$$A \sim \text{COLOR} \otimes \text{BLUE} + \text{MATERIAL} \otimes \text{METAL} + \text{SHAPE} \otimes \text{SPHERE} := S_A$$

$$B \sim \text{COLOR} \otimes \text{BLUE} + \text{MATERIAL} \otimes \text{METAL} + \text{SHAPE} \otimes \text{CUBE} := S_B$$

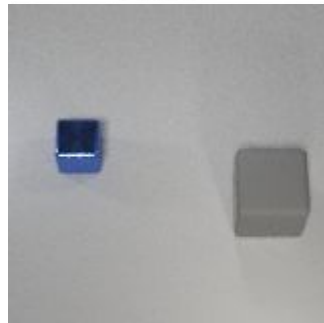
$$C \sim \text{COLOR} \otimes \text{BROWN} + \text{MATERIAL} \otimes \text{RUBBER} + \text{SHAPE} \otimes \text{SPHERE} := S_C$$

$$D \sim \text{COLOR} \otimes \text{BROWN} + \text{MATERIAL} \otimes \text{RUBBER} + \text{SHAPE} \otimes \text{CUBE} := S_D$$

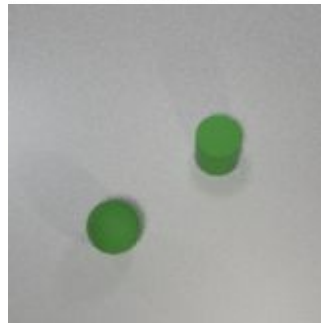
Scene A



Scene B



Scene C



Scene D



A : B

C : D

$$A \sim \text{SMALL} \otimes \text{BLUE} \otimes \text{METAL} \otimes \text{CYLINDER} + \rho(\text{SMALL} \otimes \text{GRAY} \otimes \text{RUBBER} \otimes \text{SPHERE}) := S_A$$

$$B \sim \text{SMALL} \otimes \text{BLUE} \otimes \text{METAL} \otimes \text{CUBE} + \rho(\text{LARGE} \otimes \text{GRAY} \otimes \text{RUBBER} \otimes \text{CUBE}) := S_B$$

$$C \sim \text{SMALL} \otimes \text{GREEN} \otimes \text{RUBBER} \otimes \text{CYLINDER} + \rho(\text{SMALL} \otimes \text{GREEN} \otimes \text{RUBBER} \otimes \text{SPHERE}) := S_C$$

$$D \sim \text{SMALL} \otimes \text{GREEN} \otimes \text{RUBBER} \otimes \text{CUBE} + \rho(\text{LARGE} \otimes \text{GREEN} \otimes \text{RUBBER} \otimes \text{CUBE}) := S_D$$

Representing relations with bind/unbinding

$$\mathbf{A} : \mathbf{B} \sim \mathbf{S}_\mathbf{A}^{-1} \otimes \mathbf{S}_\mathbf{B} = \mathbf{CYLINDER}^{-1} \otimes \mathbf{CUBE} + \rho(\mathbf{SMALL}^{-1} \otimes \mathbf{LARGE} \otimes \mathbf{SPHERE}^{-1} \otimes \mathbf{CUBE}) + \boldsymbol{\eta}_1$$

$$\mathbf{C} : \mathbf{D} \sim \mathbf{S}_\mathbf{C}^{-1} \otimes \mathbf{S}_\mathbf{D} = \mathbf{CYLINDER}^{-1} \otimes \mathbf{CUBE} + \rho(\mathbf{SMALL}^{-1} \otimes \mathbf{LARGE} \otimes \mathbf{SPHERE}^{-1} \otimes \mathbf{CUBE}) + \boldsymbol{\eta}_2$$

$$\mathbf{S}_\mathbf{A}^{-1} \otimes \mathbf{S}_\mathbf{B} \otimes \mathbf{S}_\mathbf{C} = \mathbf{S}_\mathbf{D} + \boldsymbol{\eta}_3$$

$\boldsymbol{\eta}_*$ represents *noise*

$$\mathbf{A} \sim \mathbf{SMALL} \otimes \mathbf{BLUE} \otimes \mathbf{METAL} \otimes \mathbf{CYLINDER} + \rho(\mathbf{SMALL} \otimes \mathbf{GRAY} \otimes \mathbf{RUBBER} \otimes \mathbf{SPHERE}) := \mathbf{S}_\mathbf{A}$$

$$\mathbf{B} \sim \mathbf{SMALL} \otimes \mathbf{BLUE} \otimes \mathbf{METAL} \otimes \mathbf{CUBE} + \rho(\mathbf{LARGE} \otimes \mathbf{GRAY} \otimes \mathbf{RUBBER} \otimes \mathbf{CUBE}) := \mathbf{S}_\mathbf{B}$$

$$\mathbf{C} \sim \mathbf{SMALL} \otimes \mathbf{GREEN} \otimes \mathbf{RUBBER} \otimes \mathbf{CYLINDER} + \rho(\mathbf{SMALL} \otimes \mathbf{GREEN} \otimes \mathbf{RUBBER} \otimes \mathbf{SPHERE}) := \mathbf{S}_\mathbf{C}$$

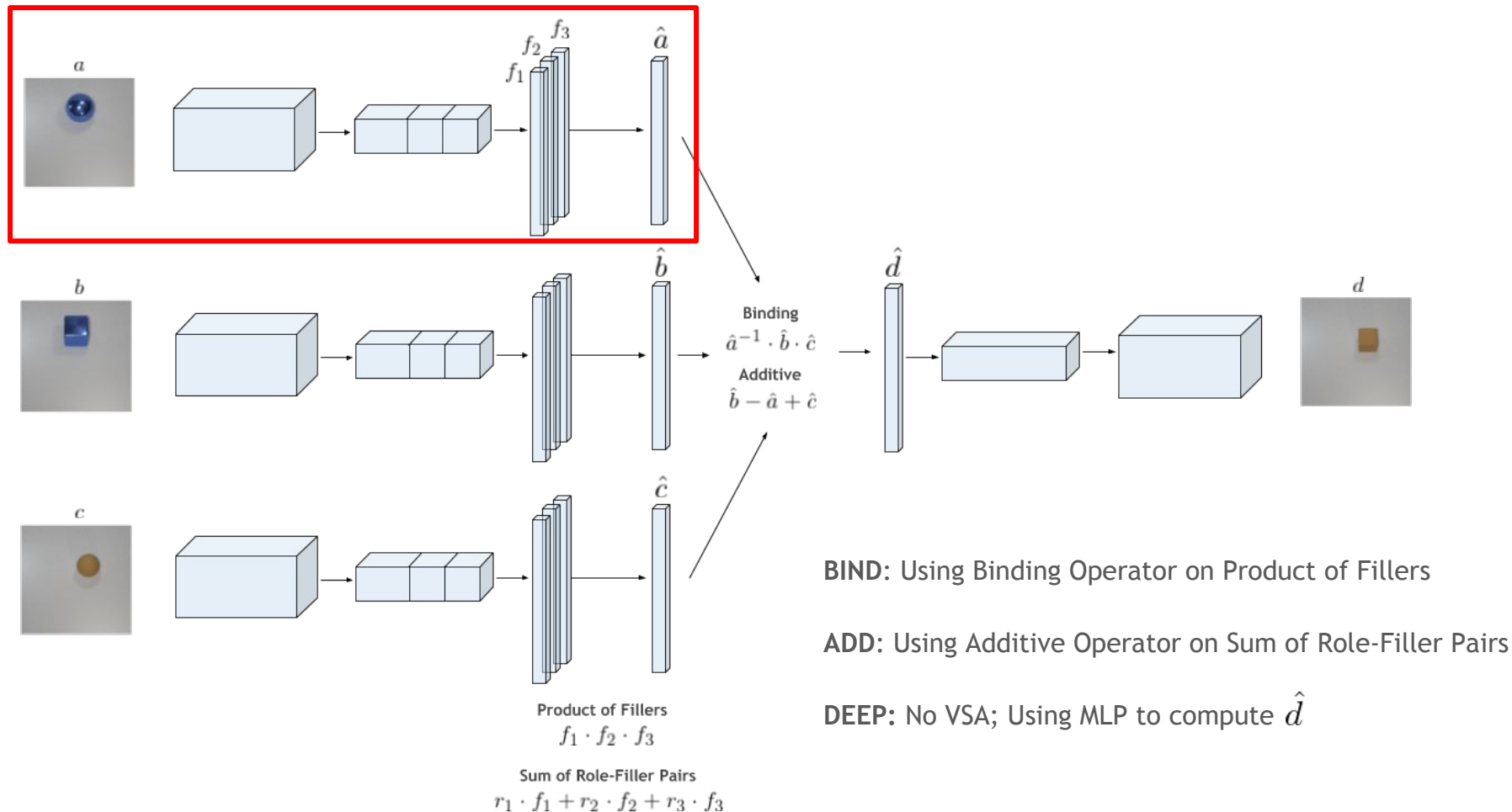
$$\mathbf{D} \sim \mathbf{SMALL} \otimes \mathbf{GREEN} \otimes \mathbf{RUBBER} \otimes \mathbf{CUBE} + \rho(\mathbf{LARGE} \otimes \mathbf{GREEN} \otimes \mathbf{RUBBER} \otimes \mathbf{CUBE}) := \mathbf{S}_\mathbf{D}$$

VSA encodings make analogical reasoning transparent and elegant

- Relations are explicitly depicted in terms of atomic factors
- Simple binding/additive operations are used to reason about analogies

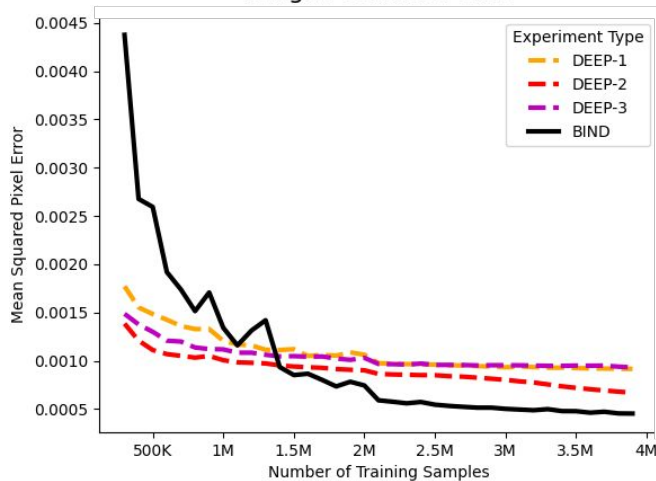
...and they can be learned with neural networks

Overview of Model Architecture

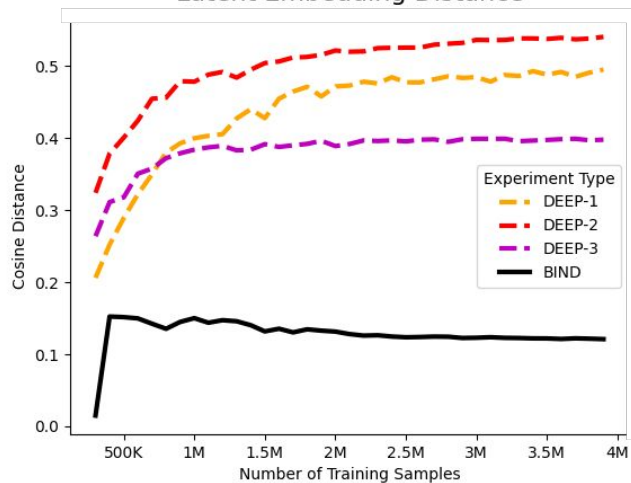


End-to-End Experiments

Image Prediction Loss

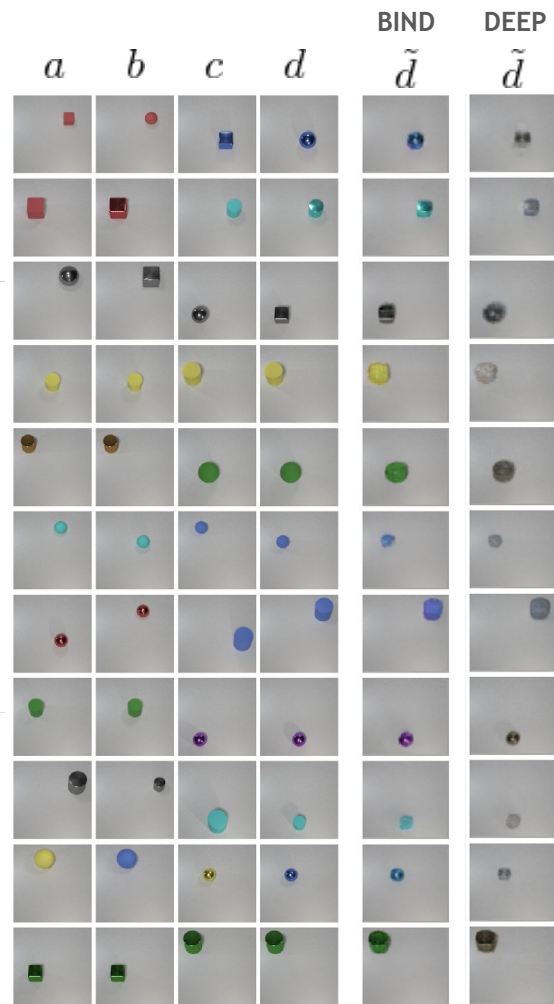


Latent Embedding Distance



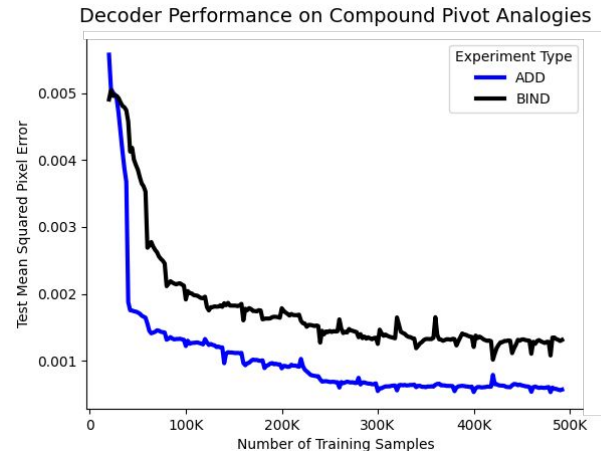
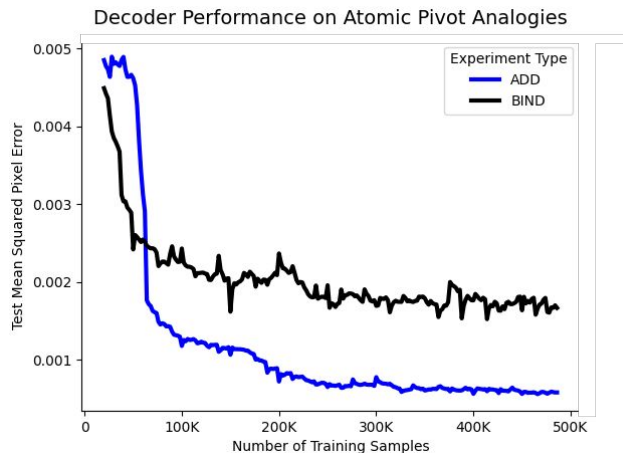
$$\text{BIND: } 1 - \text{sim}(\hat{a}^{-1} \cdot \hat{b} \cdot \hat{c}, \hat{d})$$

$$\text{DEEP: } 1 - \text{sim}(\text{MLP}(\hat{a}, \hat{b}, \hat{c}), \hat{d})$$



The Difficulty of Decoding

How do different VSA representations affect decoder performance?



Filler variables are easily accessible using sum of Role-Filler Pairs representation

$$r_1^{-1} \cdot (r_1 \cdot f_1 + r_2 \cdot f_2 + r_3 \cdot f_3) \approx f_1$$

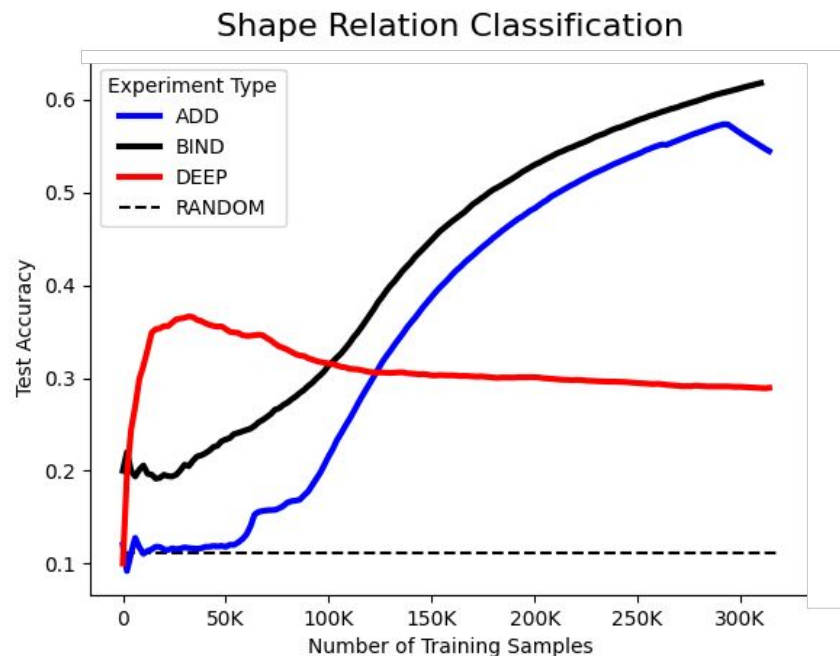
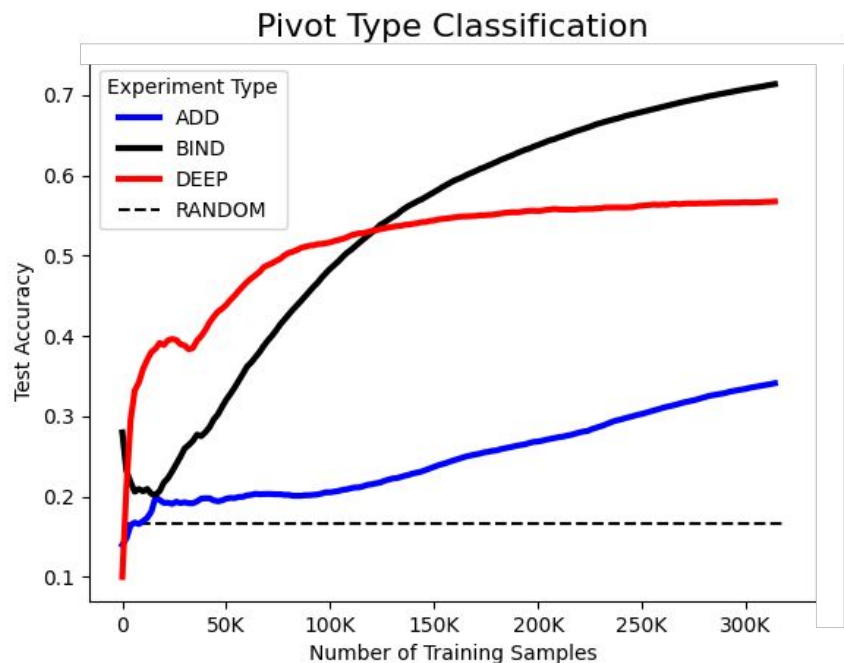
Difficult for deep networks to factorize Product of Fillers representation, but better solutions exist [1][2]

[1] Frady, E., Kent, S., Olshausen, B., & Sommer, F. (2020). Resonator Networks, 1. *Neural Computation*, to appear (preprint: arXiv:2007.03748)

[2] Kent, S., Frady, E., Sommer, F., & Olshausen, B. (2020). Resonator Networks, 2: *Neural Computation*, to appear (preprint: arXiv:1906.11684)

Encoder for Relation Classification

Do structured representations efficiently uncover the relation defining the analogy?



Conclusion

- Representing objects with structured representations (e.g. VSAs) makes modeling and reasoning about analogies simple and transparent
- Reasoning is downstream from the encoding problem.
- Deep learning can be used to learn these structured representations and support analogical reasoning.
 - Work to be done on 1) self-supervised (and decoding-free) training strategies and 2) principles of design for deep learning encoders.

References

- Forbus, K. D., Gentner, D., & Law, K. (1995). MAC/FAC: A model of similarity-based retrieval. *Cognitive science*, 19(2), 141-205.
- Frady, E., Kent, S., Olshausen, B., & Sommer, F. (2020). Resonator Networks, 1. An efficient solution for factoring high-dimensional, distributed representation of data structures. *Neural Computation*, 32(12), 2311-2331.
- Gentner, D. (1983). Structure-mapping: A theoretical framework for analogy. *Cognitive science*, 7(2), 155-170.
- Hummel, J. E., & Holyoak, K. J. (1997). Distributed representations of structure: A theory of analogical access and mapping. *Psychological review*, 104(3), 427.
- Kent, S., Frady, E., Sommer, F., & Olshausen, B. (2020). Resonator Networks, 2: Factorization performance and capacity compared to optimization-based methods. *Neural Computation*, 32(12), 2332-2388.
- Maudgalya, N., Olshausen, B. A., & Kent, S. J. (2020). Vector symbolic visual analogies. In *AAAI Symposium on Conceptual Abstraction and Analogy in Natural and Artificial Intelligence*.
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Extra slides

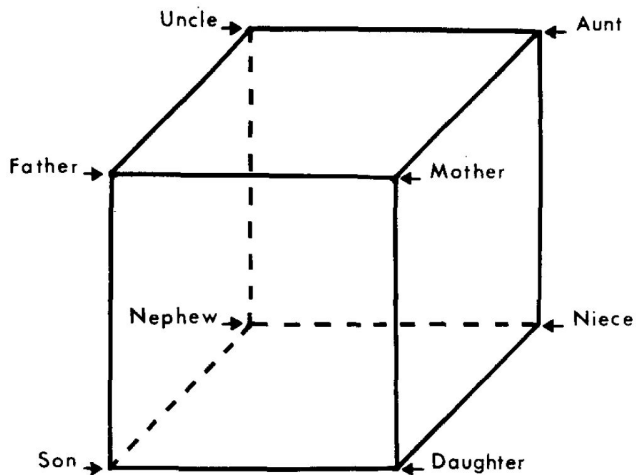


FIG. 2. Three-dimensional representation of relations among eight kinship terms.

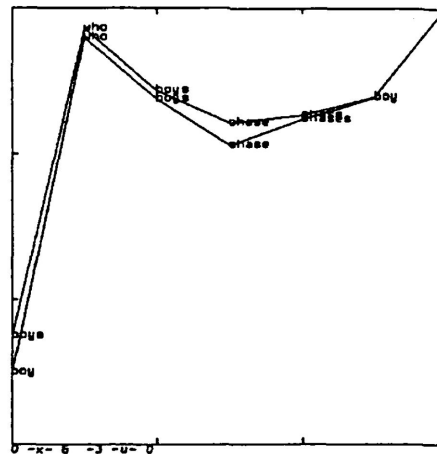


Figure 8
Trajectories through state space for sentences (8c)
and (8d).

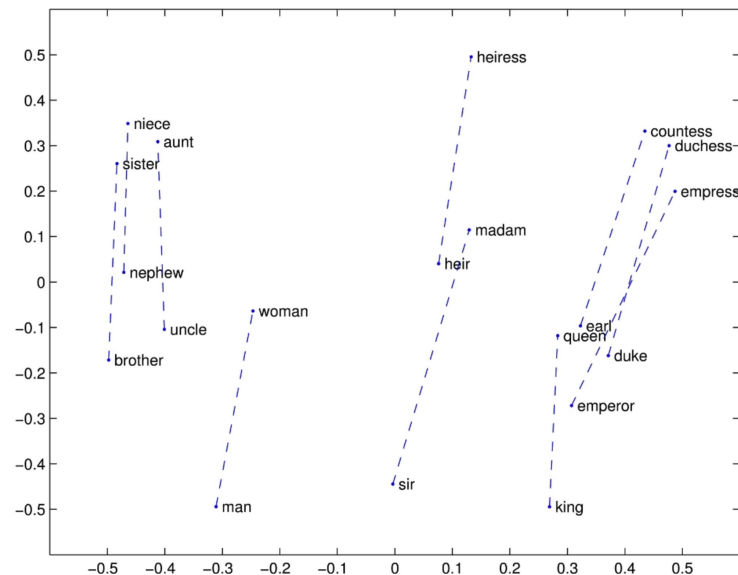
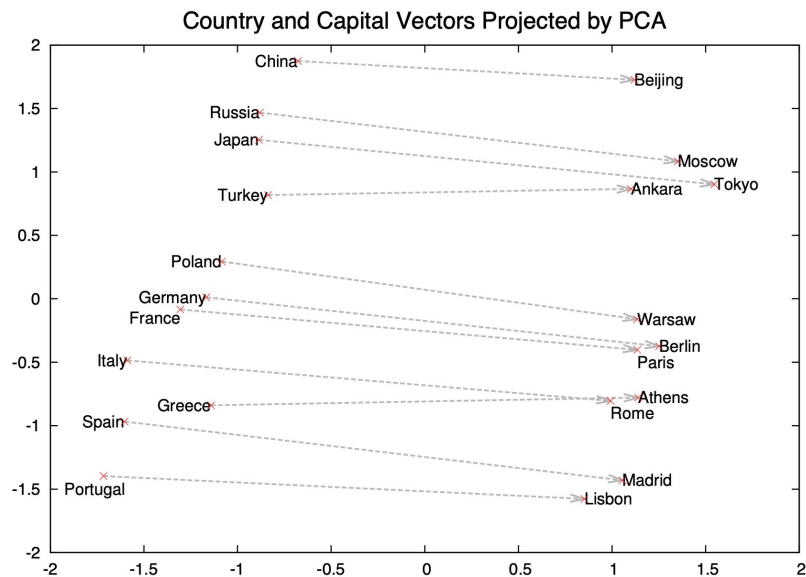
(8c) boy who boys chase chases boy .

(8d) boys who boys chase chase boy .

[1] Rumelhart, D. E., & Abrahamson, A. A. (1973). A model for analogical reasoning. *Cognitive Psychology*, 5(1), 1-28.

[2] Elman, J. L. (1989). Representation and structure in connectionist models. *UCSD La Jolla Center for Research in Language*.

Analogies on encodings of words



- [1] Mikolov, T., Chen, K., Corrado, G., & Dean, J. (2013). *arXiv:1301.3781*.
- [2] Mikolov, T., Yih, W. T., & Zweig, G. (2013). *NAACL-HLT*
- [3] Mikolov, T., Sutskever, I., Chen, K., Corrado, G. S., & Dean, J. (2013). *NeurIPS*.
- [4] Pennington, J., Socher, R., & Manning, C. D. (2014). *EMNLP*.

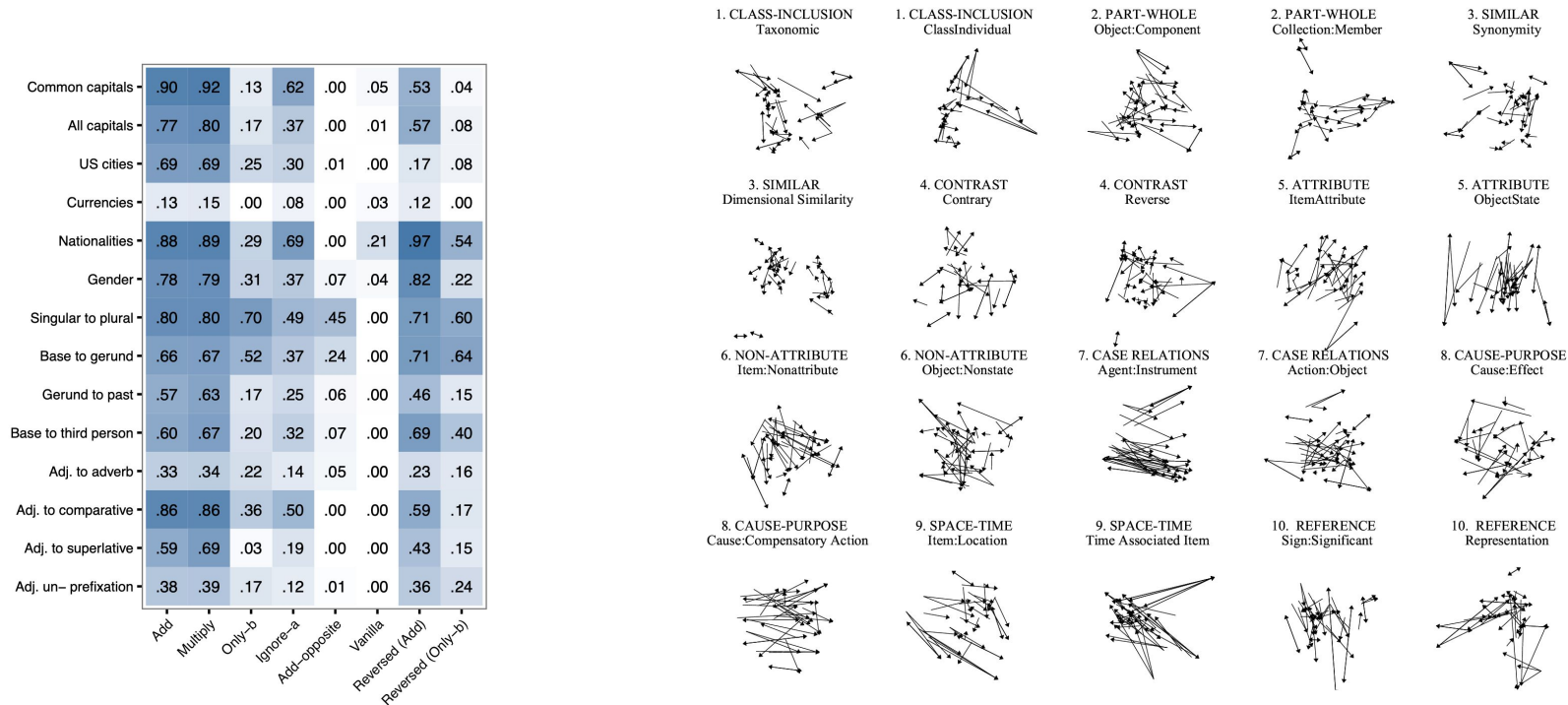
“Somewhat surprisingly, many of these patterns can be represented as linear translations.” [1]

“Since vector spaces are inherently linear structures, the most natural way to do this is with vector differences” [2]

[1] Mikolov, T., Sutskever, I., Chen, K., Corrado, G. S., & Dean, J. (2013). *NeurIPS*.

[2] Pennington, J., Socher, R., & Manning, C. D. (2014). *EMNLP*.

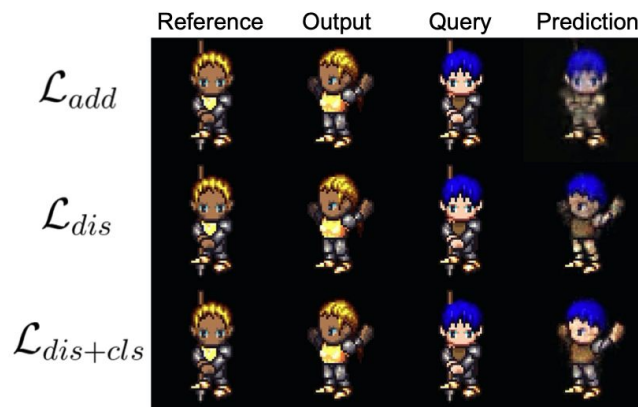
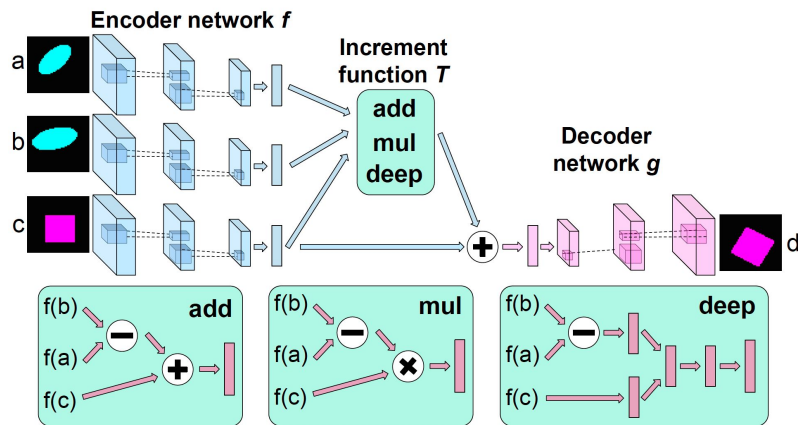
Why should relations be captured with sum/difference?



[1] Linzen, T. (2016). Issues in evaluating semantic spaces using word analogies. *arXiv preprint arXiv:1606.07736*.

[2] Chen, D., Peterson, J. C., & Griffiths, T. L. (2017). Evaluating vector-space models of analogy. *arXiv preprint arXiv:1705.04416*.

Visual analogies



References for extra slides

- Chen, D., Peterson, J. C., & Griffiths, T. L. (2017). Evaluating vector-space models of analogy. *arXiv preprint arXiv:1705.04416*.
- Elman, J. L. (1989). Representation and structure in connectionist models. *UCSD La Jolla Center for Research in Language*.
- Linzen, T. (2016). Issues in evaluating semantic spaces using word analogies. *arXiv preprint arXiv:1606.07736*.
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- Mikolov, T., Chen, K., Corrado, G., & Dean, J. (2013). Efficient estimation of word representations in vector space. *arXiv preprint arXiv:1301.3781*.
- Mikolov, T., Yih, W. T., & Zweig, G. (2013). Linguistic regularities in continuous space word representations. In *Proceedings of the 2013 conference of the north american chapter of the association for computational linguistics: Human language technologies* (pp.746-751).
- Pennington, J., Socher, R., & Manning, C. D. (2014, October). Glove: Global vectors for word representation. In *Proceedings of the 2014 conference on empirical methods in natural language processing (EMNLP)* (pp. 1532-1543).
- Reed, S. E., Zhang, Y., Zhang, Y., & Lee, H. (2015). Deep visual analogy-making. In *Advances in neural information processing systems* (pp. 1252-1260).
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